

Nonoscillation of First-order Neutral Difference Equation

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Abstract

The oscillation of the first order neutral difference equation $\Delta[x(n) - px(n-\tau)] + qx(n-\sigma) = 0$ is studied in this paper, where p > 0 or p < 0, q is a positive constant, σ is a non-negative integer, τ is a positive integer. The sufficient conditions for nonoscillation of the equation is obtained by suitable inequality and characteristic equation.

Keywords: Difference equation, Neutral, Nonoscillation

1. Introduction

Qualitative behavior of solutions of difference equations has received considerable interest recently. In [1] the oscillation of the first order neutral difference equation

$$\Delta[x(n) - px(n-\tau)] + qx(n-\sigma) = 0, \qquad (1)$$

was considered and some oscillation criterias were given, q is a positive constant, σ is a non-negative integer, τ is a positive integer. In this paper nonoscillation of the solutions of the equation (1) are studied, where p > 0 or p < 0 and Δ is the forward difference, i.e., $\Delta x_n = x_{n+1} - x_n$.

A solution of equation (1) is called oscillatory, if it is neither finally positive nor negative. Otherwise it is called nonoscillatory.

2. main result

Lemma 1^[2] A necessary and sufficient condition for all solutions of equation (1) to oscillate is that the characteristic equation</sup>

$$F(\lambda) = (\lambda - 1)\lambda^{\sigma - \tau} (\lambda^{\tau} - p) + q = 0$$
⁽²⁾

has no positive real root.

Theorem 1 Assume that p < 0.q is a positive constant, σ is a non-negative integer and τ is a positive integer, all solutions of equation (1) are nonoscillatory.

Proof: Since $F(\lambda) = (\lambda - 1)\lambda^{\sigma-\tau}(\lambda^{\tau} - p) + q = 0$ and q < 0, the equation (2) possibly has roots on interval $(1, \infty)$. Obviously F(1) = q < 0. From p < 0 we can get

$$F(\lambda) = (\lambda - 1)\lambda^{\sigma - \tau} \left(\lambda^{\tau} - p\right) + q = (\lambda - 1) \left(\lambda^{\sigma} - \frac{p}{\lambda^{\tau - \sigma}}\right) + q > (\lambda - 1)\lambda^{\sigma} + q$$

Assume that $G(\lambda) = (\lambda - 1)\lambda^{\sigma} + q$, the values of $G(\lambda)$ increase on interval $(1, \infty)$. Obviously when $\lambda \to \infty$, $G(\lambda) \to \infty$. So there is a positive constant N, such that G(N) > 0. From $F(\lambda) > G(\lambda)$ we can get F(N) > 0. So F(N)F(1) < 0, and $F(\lambda)$ is continuous on interval [1, N], we can get there is at least a point ζ on interval (1, N) such that $F(\zeta) = 0$. Therefore the equation (2) has roots on $(1, \infty)$, so all solutions of equation (1)

are nonoscillatory.

Theorem 2 Assume that p > 0.q is a positive constant, σ is a non-negative integer and τ is a positive integer, all solutions of equation (1) are nonoscillatory.

Proof: When 1 > p > 0, Obviously the equation (2) has positive roots only on $\lambda \in (1,\infty) \cup \left(0, p^{\frac{1}{\tau}}\right)$. F(1) = q < 0.

When $\sigma - \tau \ge 0$, the values of $F(\lambda)$ increase on interval $(1,\infty)$. Obviously when $\lambda \to \infty$, we can get $F(\lambda) \to \infty$. So there is a positive constant M_1 , such that $F(M_1) > 0$. So $F(M_1)F(1) < 0$, and $F(\lambda)$ is continuous on interval $[1, M_1]$, we can get there is at least a point ξ_1 on $(1, M_1)$ such that $F(\xi_1) = 0$. Therefore the equation (2) has a root at least on interval $(1, \infty) \cup \left(0, p^{\frac{1}{\tau}}\right)$ and all solutions of equation (1)

are nonoscillatory.

When $\sigma - \tau < 0$, we can get

$$F(\lambda) = (\lambda - 1)\lambda^{\sigma - \tau} \left(\lambda^{\tau} - p\right) + q = (\lambda - 1) \left(\lambda^{\sigma} - \frac{p}{\lambda^{\tau - \sigma}}\right) + q$$

Obviously when $\lambda \to \infty$, we have $\frac{p}{\lambda^{\tau-\sigma}} \to 0$ and $F(\lambda) \to \infty$. So there is a positive constant M_2 such that $F(M_2) > 0$. So $F(M_2)F(1) < 0$, and $F(\lambda)$ is continuous on interval $[1, M_2]$, we can get there is at least a point ξ_2 on interval $(1, M_2)$ such that $F(\xi_2) = 0$. Therefore the equation (2) has a root at least on interval $(1, \infty)$. So the equation (2) has a root at least on interval $(1, \infty) \cup \left(0, p^{\frac{1}{\tau}}\right)$ and all solutions of equation (1) are nonoscillatory.

When p = 1, obviously the equation (2) has positive roots only on interval $(1, \infty) \cup (0,1)$. The process of the proof is similar with above-mentioned. We can get the equation (2) has a root at least on interval $(1, \infty) \cup (0,1)$. So all solutions of equation (1) are nonoscillatory.

When p > 1, obviously the equation (2) has positive roots only on interval $\left(p^{\frac{1}{\tau}}, \infty\right) \cup (0,1)$. The process of the proof is

similar with above-mentioned. We can get the equation (2) has a root at least on interval $\left(p^{\frac{1}{\tau}},\infty\right) \cup (0,1)$. So all

solutions of equation (1) are nonoscillatory.

3. Examples

Example 1.Consider difference equation $\Delta(x_n + 2x_{n-3}) - 4x_{n-2} = 0$ where $p = -2, \tau = 3$,

$$\sigma = 2, q = -4$$

So the conditions in theorem 1 are satisfied and the characteristic equation is

$$F(\lambda) = (\lambda - 1)\lambda^{-1}(\lambda^3 + 2) - 4 = 0$$
⁽³⁾

From the figure 1 we can see the equation (2) has a real root. Therefore all solutions of equation (1) are nonoscillatory.

Example 2.Consider difference equation
$$\Delta \left(x_n - \frac{1}{2} x_{n-1} \right) - 2x_{n-3} = 0$$
 where $p = \frac{1}{2}, \tau = 1$

 $\sigma = 3$, q = -2.

So the conditions in theorem 2 are satisfied and the characteristic equation is

$$F(\lambda) = (\lambda - 1)\lambda^2 \left(\lambda - \frac{1}{2}\right) - 2 = 0$$
(4)

From the figure 2 we can see the equation (2) has a real root. Therefore all solutions of equation (1) are nonoscillatory.

Example 3. Consider difference equation $\Delta \left(x_n - \frac{1}{2} x_{n-3} \right) - 2x_{n-1} = 0$, where $p = \frac{1}{2}, \tau = 3$,

 $\sigma = 1$, q = -2.

So the conditions in theorem 2 are satisfied and the characteristic equation is

$$F(\lambda) = (\lambda - 1)\lambda^{-2} \left(\lambda^3 - \frac{1}{2}\right) - 2 = 0$$
(5)

From the figure 3 we can see the equation (2) has no real root. Therefore all solutions of equation (1) are oscillatory.

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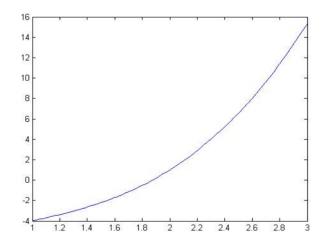


Figure 1. The figure of (3) on interval (-4,16)

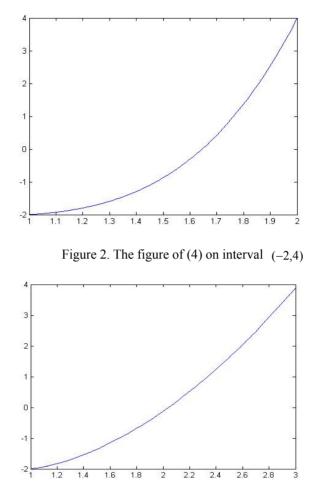


Figure 3. The figure of (5) on interval (-2,4)