Minimum Hellinger Distance Estimation of a Univariate GARCH Process

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Abstract

In this paper, we determine the Minimum Hellinger Distance estimator of a stationary GARCH process. We construct an estimator of the parameters based on the minimum Hellinger distance method. Under conditions which ensure the ϕ-mixing of the GARCH process, we establish the almost sure convergence and the asymptotic normality of the estimator.

Keywords. Hellinger distance estimation, GARCH process, ϕ-mixing process, consistence, asymptotic normality.

1. Introduction

General Autoregressive conditionally heteroscedastic (GARCH) models were pioneered by Engle(1982) and Bollerslev(1986), and have ever since been widely used to analyze financial time series. Parameters of GARCH models are usually estimated by the quasi-maximum likelihood estimator (QMLE) (Berkes, Horváth, & Kokoszka, 2003) and (Francq & Zakoïan, 2004). The QML estimator is well-known for its efficiency asymptotic properties under regular conditions, however it has very bad robustness properties.

In this paper we estimate the parameters of GARCH process using the minimum Hellinger distance (MHD) method, under uniform mixing (or ϕ-mixing) condition.

The interest for this method of parametric estimation is that the minimum Hellinger distance estimation method gives efficient and robust estimators (Beran, 1977). The minimum Hellinger distance estimators have been used in parameter estimation for independent observations (Beran, 1977), for nonlinear time series models (Hili, 1995) and recently for univariate long memory linear processes (Bitty & Hili, 2010), for nonlinear univariate and multivariate gaussian process (N’dri & Hili, 2011, 2013), for parameter estimation of one-dimensional diffusion process (Apala & Hili, 2013).

The paper is organized as follows. In section 2 we give the definition and some properties of the GARCH model. Section 3 contains the definition of the estimator and some assumptions. Sections 4 and 5 are the main results of the paper. They respectively establish the consistency and the asymptotic normality of the estimator θ_n. In section 6 we did some numerical simulations. In section 7 we apply MHD method to a financial time series. In section 8 we open problem.

2. Definition and Some Properties of GARCH Model

Definition 2.1. The process \((X_t)_{t \in \mathbb{Z}}\) is called a GARCH\((p, q)\) if

\[
X_t = \varepsilon_t \sqrt{h_t},
\]

where \(\varepsilon_t\) are i.i.d random variables, with \(E(\varepsilon_t) = 0, E(\varepsilon_t^2) = 1\) and

\[
h_t = \sigma_t^2 = w + \sum_{i=1}^{p} \alpha_i X_{t-i}^2 + \sum_{i=1}^{q} \beta_i h_{t-i}.
\]

The \(\alpha_i\) and \(\beta_i\) are nonnegative constants and \(\omega\) is a (strictly) positive constant.

\[
\theta = (w, \alpha_1, ..., \alpha_p, \beta_1, ..., \beta_q)^T \in \Theta \subset \mathbb{R}^{p+q+1} \text{ is the vector of the parameters of interest and } \theta_0 = (\omega_0, \alpha_{01}, ..., \alpha_{0q}, \beta_{01}, ..., \beta_{0p})^T \text{ the vector of the true values, where } T \text{ denotes the transpose.}
\]
Proposition 2.1 (Bollerslev, 1986, Theorem 1). If

\[ \sum_{i=1}^{p} a_i + \sum_{i=1}^{q} b_i < 1, \]

then, the GARCH(p, q) process \((X_t)_{t \in \mathbb{Z}}\) defined in (1.2) admits a unique strictly stationary solution.

For the following properties see Davis & Mikosch (2008).

Proposition 2.2. If \(\varepsilon_t\) has a positive Lebesgue density on a neighborhood of 0, the strictly stationary GARCH process \((X_t)\) defined in (2.1) is \(\phi\)-mixing, moreover, the mixing rate \(\phi_k\) decays to 0 geometrically \((\phi_k \leq C \rho^k \text{ with } C > 0 \text{ and } 0 < \rho < 1)\).

3. Definition of the Estimator and Some Assumptions

Let \(X_1, \ldots, X_n\) be an observed sequence of GARCH processes with the density belonging to a specified parametric family \(\{f_\theta\}_{\theta \in \Theta}\) where \(\Theta\) is the parameter espace, a compact set of \(\mathbb{R}^{p+q+1}\). Note that in our study the form of the density is not explicit.

Let \(f_n\) be a nonparametric estimator of the density \(f_\theta\) defined as

\[ f_n(x) = \frac{1}{nb_n} \sum_{t=1}^{n} K\left(\frac{x-X_t}{b_n}\right), \quad x \in \mathbb{R} \]

where \(K(\cdot)\) is a kernel function and \((b_n)\) is a sequence of bandwidths.

The Minimum Hellinger Distance estimator \(\hat{\theta}_n\) of \(\theta_0\) is the value in the parameter espace \(\Theta\) which minimizes the Hellinger distance (denoted \(H_2\)) between \(f_n\) and \(f_\theta\) defined by:

\[ \hat{\theta}_n = \arg \min_{\theta \in \Theta} H_2(f_n; f_\theta), \quad \text{(3.1)} \]

\[ H_2(f_n; f_\theta) = \left\{ \int_{\mathbb{R}} \left| f_n^2(x) - f_\theta^2(x) \right|^2 dx \right\}^{\frac{1}{2}}. \]

To establish the asymptotic properties of the estimator \(\hat{\theta}_n\), we need the following assumptions.

Assumption A1

The GARCH(p,q) process is geometrically \(\phi\)-mixing.

Assumption A2

For each \(\theta \in \Theta\), the density \(f_\theta\) of \(X_t\) is positive over all \(\mathbb{R}\) and twice continuously differentiable.

Assumption A3

For each \(\theta \in \Theta\), \(\left\| f_\theta^{(i)} \right\|_\infty = \sup_x |f_\theta^{(i)}(x)| < \infty \quad i = 0, 1, 2\).

Assumption A4

We chose \(b_n\) such that \(\lim_{n \to \infty} b_n = 0\), \(\lim_{n \to \infty} nb_n = +\infty\), \(\lim_{n \to \infty} \sqrt{nb_n^2} = +\infty\), and \(\lim_{n \to \infty} n^3 b_n^2 = 0\).

Assumption A5

The continuous function \(K\) is symmetric positive, bounded function with compact support such that:

\[ \int_{\mathbb{R}} K(u) du = 1, \quad \int_{\mathbb{R}} u K(u) du = 0 \text{ and } \int_{\mathbb{R}} |u|^2 K(u) du < \infty. \]

Assumption A6

For \(\theta_1, \theta_2 \in \Theta\), \(\theta_1 \neq \theta_2\) implies that \(\{ x \in \mathbb{R} / f_{\theta_1}(x) \neq f_{\theta_2}(x) \}\) is a set of positive Lebesgue measure.
4. Consistency of the Estimator \( \hat{\theta}_n \)

**Theorem 4.1** (Almost sure convergence). Suppose that assumptions (A1)-(A6) are satisfied. If \( \theta_0 \) is in the interior of \( \Theta \), then, \( \hat{\theta}_n \rightarrow \theta_0 \) a.s when \( n \rightarrow +\infty \).

**Proof of theorem 4.1.**

Let \( F \) denote the set of all densities with respect to the Lebesgue measure on \( \mathbb{R} \).

Define the functional \( U: F \rightarrow \Theta \) as

\[
U(g) = \arg \min_{\theta \in \Theta} H_2(g, f_\theta),
\]

provided such minimum exists. In case \( U(g) \) is multiple-value, the notation \( U(g) \) will represent one of possible values chosen arbitrarily.

We have

\[
|f_n(x) - f_{\theta}(x)| \leq |f_n(x) - Ef_n(x)| + |Ef_n(x) - f_{\theta}(x)|.
\]

By lemmas 4.2 and 4.3

\[
|f_n(x) - f_{\theta}(x)| \rightarrow 0 \text{ almost surely when } n \rightarrow \infty,
\]

consequently,

\[
\text{Pr} \left\{ \lim_{n \rightarrow \infty} f_n^2(x) = f_{\theta}^2(x) \text{ for all } x \right\} = 1.
\]

Since

\[
\int_{\mathbb{R}} f_n(x) dx = \int_{\mathbb{R}} f_{\theta}(x) dx = 1,
\]

then,

\[
H_2(f_n, f_{\theta}) = \left\{ \int_{\mathbb{R}} \left( f_n^2(x) - f_{\theta}^2(x) \right)^{\frac{1}{2}} dx \right\} \rightarrow 0 \text{ a.s when } n \rightarrow \infty.
\]

Thus \( f_n(x) \rightarrow f_{\theta}(x) \) a.s when \( n \rightarrow \infty \) in the Hellinger topology.

From the continuity of the functional \( U \) (Beran, 1977, Theorem 1), we obtain

\[
\hat{\theta}_n = U(f_n(x)) \rightarrow U(f_{\theta}(x)) = \theta_0 \text{ a.s when } n \rightarrow \infty.
\]

**Lemma 4.2.** Suppose that assumptions (A1)-(A5) are satisfied. Then,

\[
|f_n(x) - Ef_n(x)| \rightarrow 0 \text{ a.s when } n \rightarrow \infty.
\]

**Proof of lemma 4.2.**

We have

\[
|f_n(x) - Ef_n(x)| = \frac{1}{nb_n} \left| \sum_{i=1}^{n} \Delta_i \right|
\]

where

\[
\Delta_i = K\left( \frac{x - X_i}{b_n} \right) - E K\left( \frac{x - X_i}{b_n} \right).
\]

Using assumption (A5) and Jensen’s inequality, we get

\[
|\Delta_i| \leq \left| K\left( \frac{x - X_1}{b_n} \right) \right| + E \left| \left( K\left( \frac{x - X_1}{b_n} \right) \right) \right|
\]

\[
\leq \left| K\left( \frac{x - X_1}{b_n} \right) \right| + E \left( \left| K\left( \frac{x - X_1}{b_n} \right) \right| \right)
\]

\[
\leq \sup_x \left| K\left( \frac{x - X_1}{b_n} \right) \right| + E \left( \sup_x \left| K\left( \frac{x - X_1}{b_n} \right) \right| \right)
\]

\[
\leq 2K_0
\]

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where $K_0$ is a constant.

We have also

$$E[|\Delta|^2] = E \left| K \left( \frac{x - X_1}{b_n} \right) - E K \left( \frac{x - X_1}{b_n} \right)^2 \right|$$

$$= E K^2 \left( \frac{x - X_1}{b_n} \right) - \left( E K \left( \frac{x - X_1}{b_n} \right)^2 \right)$$

$$\leq E K^2 \left( \frac{x - X_1}{b_n} \right)$$

$$= \int_{\mathbb{R}} K^2 \left( \frac{x - s}{b_n} \right) f_\theta(s) ds$$

$$\leq \int_{\mathbb{R}} K^2 \left( \frac{x - s}{b_n} \right) \sup_{s \in \mathbb{R}} f_\theta(s) ds$$

$$= \sup_{s \in \mathbb{R}} f_\theta(s) \int_{\mathbb{R}} K^2(u) du$$

$$= C b_n \leq K_1,$$

where $C = \sup_{s \in \mathbb{R}} \int_{\mathbb{R}} K^2(u) du$ and $K_1$ is a constant.

Then, by the relation (20) in Hang et al (2015) and for all $\epsilon > 0$, we obtain

$$P \left( n^{-\frac{1}{2}} \left| \sum_{i=1}^{n} \Delta_i \right| > \epsilon \right) = P \left( \frac{1}{n} \left| \sum_{i=1}^{n} \Delta_i \right| > n^{-\frac{1}{2}} \epsilon \right)$$

$$\leq 2 \exp \left\{ - \frac{\left( n^{-\frac{1}{2}} \epsilon \right) n}{8C_\phi \left( 4K_1 + 2K_0 n^{-\frac{1}{2}} \right)} \right\}$$

$$= 2 \exp \left\{ - \frac{\epsilon^2 \sqrt{nb_n}}{8C_\phi \left( 4K_1 + 2K_0 n^{-\frac{1}{2}} b_n \right)} \right\},$$

where $C_\phi = \sum_{k=1}^{\infty} \phi_k$.

We have

$$C_\phi = \sum_{k=1}^{\infty} \phi_k < \infty \text{ and } \lim_{n \to \infty} n^{-\frac{1}{2}} b_n = 0.$$

Then, using assumption (A4) and Borel Cantelli’s lemma, we get

$$n^{\frac{1}{2}} |f_n(x) - E f_n(x)| \longrightarrow 0 \ a.s \ \text{when } n \to \infty . \ \ \ (4.1)$$

Hence

$$|f_n(x) - E f_n(x)| = o \left( n^{-\frac{1}{2}} \right) \ a.s \ \text{when } n \to \infty .$$

**Lemma 4.3.** Suppose that assumptions (A1)-(A5) are satisfied. Then,

$$\sup_{x \in \mathbb{R}} \left| E f_n(x) - f_\theta(x) \right| \longrightarrow 0 \ \text{when } n \to \infty .$$
Proof of lemma 4.3.
Using assumption (A5) and the Taylor’s expansion in a neighbourhood of \(x\), we have

\[
E f_n(x) - f_0(x) = E \left( \frac{1}{nb_n} \sum_{i=1}^{n} K \left( \frac{x - X_i}{b_n} \right) \right) - f_0(x)
\]

\[
= \frac{1}{b_n} E \left( K \left( \frac{x - X_1}{b_n} \right) \right) - f_0(x)
\]

\[
= \frac{1}{b_n} \int_{\mathbb{R}} K \left( \frac{x - s}{b_n} \right) f_0(s) ds - f_0(x)
\]

\[
= \int_{\mathbb{R}} K(u) f_0(x - b_n u) du - \int_{\mathbb{R}} K(u) f_0(0) + b_n f_0'(x) \int_{\mathbb{R}} u K(u) du
\]

\[
= \int_{\mathbb{R}} K(u) \left[ f_0(x) - b_n u f_0'(x) + \frac{1}{2} b_n^2 u^2 f_0''(0) \right] du
\]

where \(\delta = x + \varphi (-b_n u)\) with \(0 < \varphi < 1\).

Then, by assumption (A3) and (A5)

\[
\sup_{x \in \mathbb{R}} |Ef_n(x) - f_0(x)| \leq \frac{1}{b_n} \sup_{x \in \mathbb{R}} |f_0'(\delta)| \int_{\mathbb{R}} |u|^2 K(u) du \leq C_1 b_n^2.
\]

Using assumption (A4), we concluded that \(\sup_{x \in \mathbb{R}} |Ef_n(x) - f_0(x)| \rightarrow 0\) when \(n \rightarrow \infty\).

5. Asymptotic Normality of the Estimator \(\hat{\theta}_n\)

For the following theorem, denote by

\[
S_\theta = f_\theta^T, \quad \dot{S}_\theta = \frac{\partial S_\theta}{\partial \theta}, \quad \ddot{S}_\theta = \frac{\partial^2 S_\theta}{\partial \theta \partial \theta^T}
\]

when these quantities exist. Furthermore, let

\[
V_\theta(x) = \left[ \int_{\mathbb{R}} \dot{S}_\theta(x) \ddot{S}_\theta^T(x) dx \right]^{-1} \ddot{S}_\theta(x)\text{ and } h_\theta(x) = \frac{\dot{S}_\theta(x)}{2 f_\theta^T(x)}.
\]

Theorem 5.1 (asymptotic normality of the estimator). Suppose that assumptions (A1)-(A6) are satisfied. Furthermore, assume that

(i) if the components of \(S_\theta\) and \(\dot{S}_\theta\) are in \(L_2\) and the norms of these components are continuous functions at \(\theta\) and

(ii) if \(\theta_0\) lies in the interior of \(\Theta\) and if \(\int_{\mathbb{R}} S_{\theta_0}(x) S_{\theta_0}(x) dx\) is a non singular \((p + q + 1) \times (p + q + 1)\)-matrix, then, the limiting distribution of \(\sqrt{n} (\hat{\theta}_n - \theta_0)\) is \(N(0, \Sigma^2)\) where

\[
\Sigma^2 = \frac{1}{4} \left[ \int_{\mathbb{R}} S_{\theta_0}(x) \dot{S}_{\theta_0}^T(x) dx \right]^{-1}
\]

Proof of theorem 5.1.

From theorem 2 of Beran (1977), we can write :
\[
\sqrt{n}(\theta_n - \theta_0) = \sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \left[ f_n^1(x) - f_{\theta_0}^1(x) \right] dx
+ \sqrt{n} A_n \int_{\mathbb{R}} S_{\theta_0}(x) \left[ f_n^2(x) - f_{\theta_0}^2(x) \right] dx
\]

where the components of \( A_n \to 0 \) when \( n \to \infty \) and \( V_{\theta_0}(x) \) defined in (5.1).

We have
\[
f_n^1(x) - f_{\theta_0}^1(x) = \frac{(f_n(x) - f_{\theta_0}(x))}{2f_{\theta_0}^1(x)} - \frac{(f_n^2(x) - f_{\theta_0}^2(x))^2}{2f_{\theta_0}^1(x)}
= \frac{(f_n(x) - f_{\theta_0}(x))}{2f_{\theta_0}^1(x)} - \frac{(f_n(x) - f_{\theta_0}(x))^2}{2f_{\theta_0}^1(x)} \left( f_n^1(x) + f_{\theta_0}^1(x) \right)^2.
\]

Thus,
\[
\sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \left[ f_n^1(x) - f_{\theta_0}^1(x) \right] dx
= \sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \frac{(f_n(x) - f_{\theta_0}(x))}{2f_{\theta_0}^1(x)} dx - \sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \frac{(f_n(x) - f_{\theta_0}(x))^2}{2f_{\theta_0}^1(x)} \left( f_n^1(x) + f_{\theta_0}^1(x) \right)^2 dx
= \sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \frac{(f_n(x) - f_{\theta_0}(x))}{2f_{\theta_0}^1(x)} dx + B_n
\]

where
\[
B_n = - \sqrt{n} \int_{\mathbb{R}} V_{\theta_0}(x) \frac{(f_n(x) - f_{\theta_0}(x))^2}{2f_{\theta_0}^1(x)} \left( f_n^1(x) + f_{\theta_0}^1(x) \right)^2 dx.
\]

Since
\[
2f_{\theta_0}^1(x) \left( f_n^1(x) + f_{\theta_0}^1(x) \right)^2 > 2f_{\theta_0}^1(x),
\]

thus,
\[
|B_n| \leq \int_{\mathbb{R}} V_{\theta_0}(x) \sqrt{n} (f_n(x) - f_{\theta_0}(x))^2 dx.
\]

Using (4.1), (4.2) and assumption (A4), we get
\[
n^{\frac{1}{2}} |f_n(x) - f_{\theta_0}(x)| \leq n^{\frac{1}{2}} |f_n(x) - E f_n(x)| + n^{\frac{1}{2}} \sup_{x \in \mathbb{R}} |E f_n(x) - f_{\theta_0}(x)|
\leq n^{\frac{1}{2}} |f_n(x) - E f_n(x)| + C_n n^{\frac{1}{2}} \to 0 \ a.s \ when \ n \to \infty.
\]

In conclusion,
\[
\sqrt{n} (f_n(x) - f_{\theta_0}(x))^2 \to 0 \ a.s \ when \ n \to \infty.
\]

Conditions (i) and (ii) of theorem 5.1 imply that \( V_{\theta_0} \) is continuous and bounded (for \( \theta_0 \) fixed), futhermore, applying Vitali’s theorem on the sequence \( \sqrt{n} (f_n(x) - f_{\theta_0}(x))^2 \), we obtain \( |B_n| \to 0 \) in probability when \( n \to \infty \).
On the other hand,
\[
\sqrt{n} \int_{\mathbb{R}} V_{n_0}(x) \frac{(f_n(x) - f_{n_0}(x))}{2f_{n_0}^2(x)} \, dx
\]
\[
= \left( \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx \right)^{-1} \int_{\mathbb{R}} \sqrt{n} S_{n_0}(x) \frac{(f_n(x) - f_{n_0}(x))}{2f_{n_0}^2(x)} \, dx
\]
\[
= \left( \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx \right)^{-1} \left( \int_{\mathbb{R}} \sqrt{n} \frac{S_{n_0}(x)}{2f_{n_0}^2(x)} f_n(x) \, dx - \frac{1}{2} \int_{\mathbb{R}} \sqrt{n} \frac{S_{n_0}(x)}{2f_{n_0}^2(x)} f_{n_0}(x) \, dx \right)
\]
\[
= \left( \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx \right)^{-1} \int_{\mathbb{R}} \sqrt{n} h_{n_0}(x) f_n(x) \, dx.
\]

Since \( A_n \to 0 \) when \( n \to \infty \), then, the limit distribution of \( \sqrt{n}(\hat{\theta}_n - \theta_0) \) is reduced to the limit distribution of
\[
\left( \int_{\mathbb{R}} \frac{\sqrt{n} S_{n_0}(x) S_{n_0}(x)^T}{2f_{n_0}^2(x)} f_n(x) \, dx \right)^{-1} \int_{\mathbb{R}} \sqrt{n} h_{n_0}(x) f_{n_0}(x) \, dx.
\]

Therefore, by the lemmas 5.3 and 5.4
\[
\int_{\mathbb{R}} \sqrt{n} h_{n_0}(x) f_n(x) \, dx \overset{D}{\to} \mathcal{N}(0, \Gamma^2) \quad \text{when} \quad n \to \infty,
\]
where
\[
\Gamma^2 = \frac{1}{4} \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx.
\]

We concluded that,
\[
\left( \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx \right)^{-1} \int_{\mathbb{R}} \sqrt{n} h_{n_0}(x) f_n(x) \, dx \overset{D}{\to} \mathcal{N}(0, \Sigma^2)
\]
where
\[
\Sigma^2 = \frac{1}{4} \left( \int_{\mathbb{R}} S_{n_0}(x) S_{n_0}(x)^T \, dx \right)^{-1}.
\]

**Lemma 5.2.** Let \( \{Y_j : j \in \mathbb{N}\} \) be a stationary sequence which is \( \phi \)-mixing with \( \sum_{j=1}^{\infty} \phi_j \frac{1}{2} < \infty \). Assume \( E|Y_1|^2 < C < \infty \) and \( E(Y_1) = 0 \). Then,
\[
\lim_{n \to \infty} \frac{1}{n} \mathbb{E} \left( \sum_{j=1}^{n} Y_j \right)^2 = \mathbb{E}(Y_1^2) + 2 \sum_{j=1}^{\infty} \mathbb{E}(Y_1 Y_{j+1})
\]

**Proof of lemma 5.2.**

Using lemma 20.1 in Billingsley (1968), we have
\[
\sum_{j=1}^{\infty} \left| \mathbb{E}(Y_1 Y_{j+1}) \right| \leq \sum_{j=1}^{\infty} 2\phi_j \left( \mathbb{E}|Y_1|^2 \right)^{\frac{1}{2}} \left( \mathbb{E}|Y_{j+1}|^2 \right)^{\frac{1}{2}}
\]
\[
\leq 2C \sum_{j=1}^{\infty} \phi_j \frac{1}{2} < \infty.
\]
Hence, the lemma follows from Ibragimov and Linnik (1971, theorem 18.5.2).

**Lemma 5.3.** Let \( h_0(.) \) the continuous function defined in (5.1). Suppose that assumptions (A1)-(A5) hold. Then,

\[
\sqrt{n} \left\{ \int_{\mathbb{R}} h_{b_n}(x) f_n(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_{b_n}(X_i) \right\} \rightarrow 0 \text{ in probability.}
\]

**Proof of lemma 5.3.**

We have

\[
\sqrt{n} \left\{ \int_{\mathbb{R}} h_{b_n}(x) f_n(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_{b_n}(X_i) \right\} = \sqrt{n} \left\{ \int_{\mathbb{R}} \frac{1}{n} \sum_{i=1}^{n} K\left( \frac{x - X_i}{b_n} \right) h_{b_n}(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_{b_n}(X_i) \right\} = \sqrt{n} \left\{ \frac{1}{n} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} \frac{1}{b_n} K\left( \frac{x - X_i}{b_n} \right) h_{b_n}(x) dx - h_{b_n}(X_i) \right) \right\}
\]

\[
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} \frac{1}{b_n} K\left( \frac{x - X_i}{b_n} \right) h_{b_n}(x) dx - h_{b_n}(X_i) \right)
\]

\[
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} K(u) h_{b_n}(X_i + ub_n) du - h_{b_n}(X_i) \int_{\mathbb{R}} K(u) du \right)
\]

\[
= \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right).
\]

Thus,

\[
E \left\{ \sqrt{n} \left\{ \int_{\mathbb{R}} h_{b_n}(x) f_n(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_{b_n}(X_i) \right\} \right\}^2
\]

\[
= E \left\{ \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right) \right\}^2
\]

\[
= \frac{1}{n} \sum_{i=1}^{n} E \left\{ \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right\}^2
\]

\[
= \frac{1}{n} \sum_{i=1}^{n} \left( \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right)^2
\]

\[
+ \frac{2}{n} \sum_{i<j} E \left\{ \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right\} \times \left( \int_{\mathbb{R}} \left( h_{b_n}(X_j + ub_n) - h_{b_n}(X_j) \right) K(u) du \right)
\]

**Step 1:** we prove that

\[
\frac{1}{n} \sum_{i=1}^{n} E \left\{ \int_{\mathbb{R}} \left( h_{b_n}(X_i + ub_n) - h_{b_n}(X_i) \right) K(u) du \right\}^2 \rightarrow 0 \text{ when } n \rightarrow \infty.
\]
Using Cauchy-Schwarz's inequality and Fubini's theorem, we obtain

\[
\frac{1}{n} \sum_{i=1}^{n} E \left( \int_{\mathbb{R}} (h_{\theta_i}(X_i + ub_n) - h_{\theta_i}(X_i)) K(u) du \right)^2
\]

\[
= \frac{1}{n} \left\{ \int_{\mathbb{R}} \left( \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x)) K(u) du \right)^2 f_{\theta_i}(x) dx \right\}
\]

\[
= \int_{\mathbb{R}} \left( \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) dx \right) du
\]

\[
\leq \int_{\mathbb{R}} \left[ \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 du \right] \left( \int_{\mathbb{R}} K^2(u) du \right) f_{\theta_i}(x) dx
\]

\[
= C_2 \int_{\mathbb{R}} \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) dudx
\]

where \( C_2 \) is a constant.

By the continuity of \( h_{\theta_i} \), we get

\[(h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 \rightarrow 0 \text{ when } n \rightarrow \infty.\]

Conditions (i) of theorem 5.1 imply that \( \hat{S}_{\theta_i} \) is bounded (for \( \theta_0 \) fixed). Then, \( h_{\theta_i} \) is also bounded (for \( \theta_0 \) fixed).

Thus, there exists a constant \( C_3 > 0 \) such that for all \( n \in \mathbb{N} \)

\[(h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 \leq C_3.\]

Since by assumption (A3) \( 0 < f_{\theta_i} < \infty \), we have

\[(h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) \rightarrow 0 \text{ when } n \rightarrow \infty\]

and for all \( n \in \mathbb{N} \)

\[(h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) \leq C_3 f_{\theta_i}(x).\]

Then, by the dominated convergence theorem,

\[
\int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) dx \rightarrow 0 \text{ when } n \rightarrow \infty
\]

where \( u \in \text{supp}(K) \) the support of kernel density \( K(.) \) a compact set.

On other hand, for all \( u \in \text{supp}(K) \) and for all \( n \in \mathbb{N} \) we obtain

\[
\left| \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) dx \right|
\]

\[
\leq C_3 \int_{\mathbb{R}} f_{\theta_i}(x) dx
\]

\[
= C_3.
\]

Therefore, by the dominated convergence theorem

\[
\int_{\mathbb{R}} \int_{\mathbb{R}} (h_{\theta_i}(x + ub_n) - h_{\theta_i}(x))^2 f_{\theta_i}(x) dxdudx \rightarrow 0 \text{ when } n \rightarrow \infty
\]

**Step 2:** we prove that

\[
\frac{2}{n} \sum_{i<j} E \left( \left( \int_{\mathbb{R}} (h_{\theta_i}(X_i + ub_n) - h_{\theta_i}(X_i)) K(u) du \right) \times \left( \int_{\mathbb{R}} (h_{\theta_j}(X_j + ub_n) - h_{\theta_j}(X_j)) K(u) du \right) \right) \rightarrow 0 \text{ when } n \rightarrow \infty.
\]
Let \( \psi \) be the function defined by:
for all \( u \in \text{supp}(K) \) a compact set and for all \( x \in \mathbb{R} \)

\[
\psi(x) = \int_{\mathbb{R}} (h_{\theta_0}(x + ub_n) - h_{\theta_0}(x)) K(u) du.
\]

\( \psi \) is a continuous function. Therefore \( \psi(X_i) \) is \( \phi \)-mixing.

We have

\[
|\psi(x)| = \left| \int_{\mathbb{R}} (h_{\theta_0}(x + ub_n) - h_{\theta_0}(x)) K(u) du \right|
\leq C_4 \int_{\mathbb{R}} K(u) du = C_4.
\]

Thus, there exists a constant \( C_5 \) such that

\[
E|\psi(X_i)|^2 < C_5.
\] (5.2)

On the other hand, we know that

\[
\phi(k) \leq C \rho^k
\]
where \( C > 0 \) and \( 0 < \rho < 1 \).

Therefore,

\[
\phi^{\frac{1}{2}}(k) \leq C \exp \left( \frac{1}{2} k \log \rho \right) = C \exp \left( \frac{1}{2} \nu k \right)
\]
with \( \nu = -\log \rho \).

Let \( \chi \) be the decreasing function defined by: for all \( k \in \mathbb{N} \)

\[
\chi(k) = C \exp \left( \frac{1}{2} \nu k \right).
\] (5.3)

We have

\[
\frac{2}{n} \sum_{i < j} E \left( \left( \int_{\mathbb{R}} (h_{\theta_0}(X_i + ub_n) - h_{\theta_0}(X_i)) K(u) du \right) \right.
\]
\[
\times \left. \left( \int_{\mathbb{R}} (h_{\theta_0}(X_j + ub_n) - h_{\theta_0}(X_j)) K(u) du \right) \right)
\]
\[
= \frac{2}{n} \sum_{i < j} E \left( \psi(X_i) \psi(X_j) \right).
\]

Using lemma 20.1 in Billingsley (1968), (5.2) and the fact that \( \chi \) is a decreasing function, we obtain
We have Proof of lemma 5.4.

\[
\frac{2}{n} \sum_{i=1}^{n} \left| E(\psi(X_i) \psi(X_j)) \right| = \frac{2}{n} \sum_{j=1}^{n-1} \left| E(\psi(X_1) \psi(X_{j+1})) \right| \\
\leq \frac{2}{n} \sum_{j=1}^{n-1} 2 \phi^{1/2}(j) \left( E|\psi(X_1)|^2 \right)^{1/2} \left( E|\psi(X_{j+1})|^2 \right)^{1/2} \\
\leq \frac{4C}{n} \sum_{j=1}^{n-1} \phi^{1/2}(j) \\
= \frac{4C}{n} \sum_{k=1}^{n-1} \phi^{1/2}(l) \\
\leq \frac{4C}{n} \sum_{k=1}^{n-1} \sum_{l=k}^{n-1} \phi^{1/2}(l) \\
= \frac{4C}{n} \sum_{k=1}^{n-1} \sum_{l=k}^{n-1} (\chi(l))^{1/2} (\chi(l))^{1/2} \\
\leq \frac{4C}{n} \sum_{k=1}^{n-1} \sum_{l=k}^{n-1} (\chi(l))^{1/2} (\chi(k))^{1/2} \\
\leq \frac{4C}{n} \sum_{k=1}^{\infty} (\chi(k))^{1/2} \sum_{l=1}^{\infty} (\chi(l))^{1/2} \\
\leq \frac{4C}{n} \left( \sum_{l=1}^{\infty} (\chi(l))^{1/2} \right)^2 ightarrow 0.
\]

By Step 1 and Step 2 we obtain

\[
E \left( \frac{1}{\sqrt{n}} \left( \int_a h_0(x) f_0(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_0(X_i) \right) \right)^2 ightarrow 0 \text{ when } n \rightarrow \infty.
\]

We concluded that,

\[
\frac{1}{\sqrt{n}} \left( \int_a h_0(x) f_0(x) dx - \frac{1}{n} \sum_{i=1}^{n} h_0(X_i) \right) \rightarrow 0 \text{ in probability.}
\]

Lemma 5.4. Suppose that assumptions (A1)-(A5) are hold. Then,

\[
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} h_0(X_i) \overset{D}{\rightarrow} N \left( 0, \Gamma^2 \right), \text{ where } \Gamma^2 = \frac{1}{4} \int \hat{S}_{\theta_0(x)} \hat{S}_{\theta_0(x)}^T dx
\]

“D” denote the convergence in distribution.

Proof of lemma 5.4.

We have

\[
E(\hat{h}_0(X_i)) = \int_R h_0(x) f_0(x) dx = \frac{1}{2} \int_R \hat{S}_{\theta_0(x)} \hat{S}_{\theta_0(x)}^T dx = 0 \tag{5.4}
\]

and

\[
E(\hat{h}_0^2(X_i)) = \int_R h_0^2(x) f_0(x) dx = \frac{1}{4} \int_R \hat{S}_{\theta_0(x)}^2 dx < \infty.
\]
We have

\[ E \left( \frac{1}{\sqrt{n}} \sum_{k=1}^{n} h_{\theta_{0}}(X_k) \right)^2 = E (h_{\theta_{0}}(X_1))^2 + \frac{2}{n} \sum_{i<j} E \left( h_{\theta_{0}}(X_i) h_{\theta_{0}}(X_j) \right) \]

and

\[ \frac{2}{n} \sum_{1 \leq i < j \leq n} \left| E \left( h_{\theta_{0}}(X_i) h_{\theta_{0}}(X_j) \right) \right| = \frac{2}{n} \sum_{j=1}^{n-1} \left| E \left( h_{\theta_{0}}(X_1) h_{\theta_{0}}(X_{j+1}) \right) \right| \]

\[ \leq \frac{2}{n} \sum_{j=1}^{n-1} 2^{j/2} (j) \left( E \left( h_{\theta_{0}}(X_1)^2 \right) \right)^{1/2} \left( E \left( h_{\theta_{0}}(X_{j+1}) \right) \right)^{1/2} \]

\[ \leq \frac{4C_0}{n} \sum_{j=1}^{n-1} j^{1/2} (j). \]

Using the same arguments as in the lemma 5.3, we can prove that

\[ \frac{2}{n} \sum_{i<j} \left| E \left( h_{\theta_{0}}(X_i) h_{\theta_{0}}(X_j) \right) \right| \leq \frac{4C_0}{n} \left( \sum_{i=1}^{\infty} (\chi(i))^{2} \right)^{1/2} \rightarrow 0, \]

where \( \chi \) is defined in (5.3).

We concluded that,

\[ E \left( \frac{1}{\sqrt{n}} \sum_{k=1}^{n} h_{\theta_{0}}(X_k) \right)^2 \rightarrow \frac{1}{4} \int_{\mathbb{R}} \sum_{\alpha=1}^{\infty} \sum_{\beta=1}^{\infty} h_{\theta_{0}}(x)^T S_{\theta_{0}}(x) dx \text{ when } n \rightarrow \infty. \]

Using the convergence limit theorem in Ibragimov (1975)

\[ \frac{1}{\sqrt{n}} \sum_{i=1}^{n} h_{\theta_{0}}(X_k) \rightarrow^{D} \mathcal{N}(0, \Gamma^2), \]

where

\[ \Gamma^2 = \frac{1}{4} \int_{\mathbb{R}} \sum_{\alpha=1}^{\infty} \sum_{\beta=1}^{\infty} h_{\theta_{0}}(x)^T S_{\theta_{0}}(x) dx \text{ when } n \rightarrow \infty. \]

6. Simulations

In this section we give some numerical simulations for minimum Hellinger distance estimator (MDHE) to show its performance. Note that the model density \( f_{\theta} \) is intractable. However, the GARCH process generating the \( X_t \) can be simulated. Thus, on the basis of \( X_t \) simulated, we can obtain the nonparametric density estimate denoted \( \hat{f}_{n,\theta} \), which becomes an alternative to intractable \( f_{\theta} \) in expression (3.1) (see Gouriéroux & Monfort, 1996). Using the method of Takada (2007), we define \( \hat{f}_{n,\theta} \) as follows:

let \( (\bar{X}_{1}^s(\theta), ..., \bar{X}_{n}^s(\theta)) \) be the \( s \)-th replication of the simulated sequence from the model GARCH, \( s = 1, 2, ..., S \). That simulated sequence has the length \( S \times n \).

\[ \bar{f}_{n,\theta}(x) = \frac{1}{S} \sum_{s=1}^{S} \left[ \frac{1}{nb_{n}} \sum_{j=1}^{n} \chi \left( \frac{\bar{X}_{j}^s(\theta) - \bar{X}_{j}^s(\theta)}{b_{n}} \right) \right], \quad x \in \mathbb{R}. \]

We generate a \( \phi \)-mixing GARCH(1,1) stationary process with true parameter \( \theta_0 = (w = 0.09, \alpha = 0.15, \beta = 0.4) \). We choose a sample length: \( n = 500 \). The process \( \varepsilon_t \) is gaussian with mean 0 and standard deviation 1. To calculate the MDH estimator, we choose the bandwidth \( b_n = n^{-0.23} \). The nonparametric estimator \( \hat{f}_{n,\theta} \) is calculated by choosing \( S = 100 \); \( b_n \) is the same for \( \hat{f}_{n,\theta} \) and \( f_{\theta} \). The kernel is gaussian with mean 0 and standard deviation 1. For the simulations, we use “fgarch and fbasics” in R packages.
To confirm the performance of the estimator, we use the sample bias and the root mean square error (RMSE) defined as follows:

$$\text{BIAS}(\theta) = \frac{1}{S} \sum_{s=1}^{S} (\theta_0 - \theta_s)$$

and

$$\text{RMSE}(\theta) = \sqrt{\frac{1}{S} \sum_{s=1}^{S} (\theta_0 - \theta_s)^2}.$$

Table 1 shows the consistency of the MHD estimator.

Table 1. Consistency of the MHD estimator and the comparison between MHDE and QMLE

<table>
<thead>
<tr>
<th></th>
<th>$\hat{\omega}$</th>
<th>$\hat{\alpha}$</th>
<th>$\hat{\beta}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>MHDE</td>
<td>0.09107473</td>
<td>0.15162636</td>
<td>0.40128264</td>
</tr>
<tr>
<td>BIAS</td>
<td>-0.00107473</td>
<td>-0.00162636</td>
<td>-0.00128264</td>
</tr>
<tr>
<td>RMSE</td>
<td>0.38581737</td>
<td>0.05417584</td>
<td>0.03038960</td>
</tr>
<tr>
<td>QMLE</td>
<td>0.08569830</td>
<td>0.17748747</td>
<td>0.30008846</td>
</tr>
<tr>
<td>BIAS</td>
<td>0.0043015</td>
<td>-0.00274874</td>
<td>0.09991154</td>
</tr>
<tr>
<td>RMSE</td>
<td>0.38228581</td>
<td>0.73444438</td>
<td>0.11449742</td>
</tr>
</tbody>
</table>

The above results show the good performance of the MHD method because all estimations biases are close to 0. Also, the table 1 shows that the estimations biases and the RMSE of the MHD method are small or almost equal to the estimation biases and the RMSE of QMLE. The MHD estimator seems better performed than the QML estimator.

To illustrate the robustness of the MHD estimator, we proceed in this manner: Let

$$f_{n, \lambda} = (1 - \lambda)f_n + \lambda \delta[0, 1],$$

where $\lambda \in [0, 1]$, and $\delta[0, 1]$ the uniform density on the interval $[0, 1]$. We vary $\lambda$ between 0 and 1 and consider the MHD associated estimator. In each case, we replace $f_n$ by $f_{n, \lambda}$. This gives the following table with nine values of $\lambda$.

Table 2. Robustness of the MHD estimator

<table>
<thead>
<tr>
<th>$\lambda$</th>
<th>$\hat{\omega}$</th>
<th>$\hat{\alpha}$</th>
<th>$\hat{\beta}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>0.08971371</td>
<td>0.14954614</td>
<td>0.39994447</td>
</tr>
<tr>
<td>0.2</td>
<td>0.08988248</td>
<td>0.14988466</td>
<td>0.40021855</td>
</tr>
<tr>
<td>0.3</td>
<td>0.09113607</td>
<td>0.15321818</td>
<td>0.39774967</td>
</tr>
<tr>
<td>0.4</td>
<td>0.09000711</td>
<td>0.14994950</td>
<td>0.40003438</td>
</tr>
<tr>
<td>0.5</td>
<td>0.09107550</td>
<td>0.15284870</td>
<td>0.40281130</td>
</tr>
<tr>
<td>0.6</td>
<td>0.08961155</td>
<td>0.14484359</td>
<td>0.39813678</td>
</tr>
<tr>
<td>0.7</td>
<td>0.08963666</td>
<td>0.14755569</td>
<td>0.39873747</td>
</tr>
<tr>
<td>0.8</td>
<td>0.08997696</td>
<td>0.15081873</td>
<td>0.40006430</td>
</tr>
<tr>
<td>0.9</td>
<td>0.08943709</td>
<td>0.14916746</td>
<td>0.39941254</td>
</tr>
</tbody>
</table>

The results of table 2 seem to indicate a certain robustness of the MHD estimator.

7. Application in Finance

The data used for our empirical study are daily returns of S&P500 index of 1272 observations. The study period is from 21-01-2009 to 02-01-2004 (cf figure 1 page 22).

We define the daily returns $r_t$ of S&P500 index as follows:

$$r_t = \log \frac{p_t}{p_{t-1}}$$

where $p_t$ is the price at the end of trading day $t$. 

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One can adjust a GARCH(1,1) model to the series \((r_t)\). Supposing that we are looking for the return at the date \(t\). Two informations are particularly interesting: the average and the variance. Particularly, we hope modeling the average and the conditional variance of \(r_t\). Then, for the GARCH modeling, it amounts to write:

\[
r_t = \mu + X_t, \tag{7.1}
\]

where

\[
X_t = \sqrt{h_t} \eta_t \quad \eta_t \sim i.i.d N(0,1)
\]

\[
h_t = w + \alpha X_{t-1}^2 + \beta h_{t-1},
\]

with \(\mu\) and \(h_t\) are respectively the conditional average and conditional variance of \(r_t\).

To estimate the parameters \((w, \alpha, \beta)\), we will use the MHD method. For that, we use the method described in the paragraph 6 with 50 replications of the model (7.1) and the bandwidth \(b_n = n^{-0.23}\). We obtain

\[
\bar{w} = 1.30022275, \quad \bar{\alpha} = 0.06422973, \quad \bar{\beta} = 0.92449759.
\]

and

\[
\bar{\mu} = -0.2311027
\]

Finally we can write,

\[
r_t = -0.2311027 + X_t
\]
where

\[ X_t = \sqrt{h_t} \eta_t, \quad \eta_t \sim i.i.d \mathcal{N}(0, 1) \]
\[ h_t = 1.30022275 + 0.06422973 X^2_{t-1} + 0.92449759 h_{t-1}. \]

8. Open problem

The multivariate GARCH process study case can be examined using the same method. Also, this study can be examined in EGARCH (Exponential GARCH) model case, IGARCH (integrated GARCH) model case and FIGARCH (Fractionary integrated GARCH) model case.

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References


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