

Existence of Solutions to the Boundary Value Problems for a Class of P-Laplacian Equations at Resonance

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Abstract

By the generalizing the extension of the continuous theorem of Ge and Ren and constructing suitable Banach spaces and operators, we investigate the existence- solutions to the boundary value problems for a class of p-Laplacian equations. Finally an example is given to illustrate our results.

Keywords: continuous theorem, resonance, p-Laplacian equations, boundary value problem

1. Introduction

In this paper, we will study the boundary value problem

$$\begin{cases} (\varphi_p(u''))'(t) = f(t, v, v', v'') \\ (\varphi_p(v''))'(t) = g(t, u, u', u'') \\ u(0) = u''(0) = 0, v(0) = v''(0) = 0 \\ u'(1) = \int_0^1 k_1(t)u'(t)dt, v'(1) = \int_0^1 k_2(t)v'(t)dt \end{cases} \quad (1.1)$$

where $\varphi_p(s) = |s|^{p-2}s$, $p > 1$, $\int_0^1 k_i(t)dt = 1$, $i = 1, 2$

In this paper, we will always suppose that

(H₁) $k_i(t) \in L^1[0, 1]$ are nonnegative and $\|k_i\|_1 = 1$, where $\|k_i\|_1 = \int_0^1 |k_i(t)| dt$, $i = 1, 2$.

(H₂) $f(t, u, v, w)$, $g(t, u, v, w)$ is continuous in $[0, 1] \times \mathbb{R}^3$

2. Preliminaries

Definition 2.1 Let X and Y be a two Banach spaces with norms $\|\cdot\|_X, \|\cdot\|_Y$, respectively. A continuous operator $M : X \cap \text{dom}M \rightarrow Y$ is said to be quasi-linear if

(i) $\text{Im}M := M(X \cap \text{dom}M)$ is a closed subset of Y ,

(ii) $\text{Ker}M := \{x \in X \cap \text{dom}M : Mx = 0\}$ is linearly homeomorphic to \mathbb{R}^n , $n < \infty$.

where $\text{dom}M$ denote the domain of operator M .

Let $X_1 = \text{Ker}M$ and X_2 be complement space of X_1 in X , then $X = X_1 \oplus X_2$. Let $P : X \rightarrow X_1$ be a projector and $\Omega \subset X$ an open and bounded set with the origin $\theta \in \Omega$

Definition 2.2 Suppose $N_\lambda : \overline{\Omega} \rightarrow Y$, $\lambda \in [0, 1]$ is a continuous and bounded operator. Denote N_1 by N . Let $\Sigma_\lambda = \{x \in \overline{\Omega} \cap \text{dom}M : Mx = N_\lambda x\}$. N_λ is said M -quasi-compact in $\overline{\Omega}$ if there exists a vector subspace Y_1 of Y satisfying $\dim Y_1 = \dim X_1$ and two operators Q, R with $Q : Y \rightarrow Y_1$, $QY = Y_1$, being continuous, bounded, and satisfying $Q(I - Q) = 0$, $R : \overline{\Omega} \times [0, 1] \rightarrow X_2 \cap \text{dom}M$ continuous and compact such that for $\lambda \in [0, 1]$,

(a) $(I - Q)N_\lambda(\overline{\Omega}) \subset \text{Im}M \subset (I - Q)Y$,

(b) $QN_\lambda x = \theta$, $\lambda \in (0, 1) \Leftrightarrow QNx = \theta$,

(c) $R(\cdot, 0)$ is zero operator and $R(\cdot, 0)|_\Sigma = (I - P)|_\Sigma$,

(d) $M[P + R(\cdot, 0)] = (I - Q)N_\lambda$

Theorem 2.1 Let X and Y be two Banach spaces with norms $\|\cdot\|_X, \|\cdot\|_Y$, respectively, and $\Omega \subset X$ be an open and bounded nonempty set. Suppose

$$M : X \cap \text{dom}M \rightarrow Y$$

is a quasi-linear operator and that $N_\lambda : \overline{\Omega} \rightarrow Y, \lambda \in [0, 1]$ is M -quasi-compact. In addition, if the following conditions hold:

(C₁) $Mx \neq N_\lambda x, \forall x \in \partial\Omega \cap \text{dom}M, \lambda \in (0, 1)$,

(C₂) $\deg(JQN, \Omega \cap \text{Ker}M, 0) \neq 0$

then the abstract equation $Mx = Nx$ has at least one solution in $\text{dom}M \cap \overline{\Omega}$, where $N = N_1, J : \text{Im}Q \rightarrow \text{Ker}M$ is a homeomorphism with $J(\theta) = \theta$.

Proof. The proof is similar to the one of lemma 2.1 and Theorem 2.1 in [Ge et al., 2004].

We can easily get the following inequalities.

Lemma2.1 For any $u, v \geq 0$, we have

(1) $\varphi_p(u, v) \leq \varphi_p(u) + \varphi_p(v), 1 < p \leq 2$.

(2) $\varphi_p(u, v) \leq 2^{p-2}(\varphi_p(u) + \varphi_p(v)), p \geq 2$.

In the following, we will always suppose that q satisfies $\frac{1}{p} + \frac{1}{q} = 1$.

3. Main Results

Let $X = C^2[0, 1] \times C^2[0, 1]$ with norm $\|(u, v)\| = \|u\| + \|v\|$, where $\|u\| = \max\{\|u\|_\infty, \|u'\|_\infty, \|u''\|_\infty\}$, $Y = C[0, 1] \times C[0, 1] \times C[0, 1] \times C[0, 1]$ with norm $\|(y_1, y_2, y_3, y_4)\| = \max\{\|y_1\|_\infty, \|y_2\|_\infty, \|y_3\|_\infty, \|y_4\|_\infty\}$ with $\|y\|_\infty = \max_{t \in [0, 1]} |y(t)|$. We know that $(X, \|\cdot\|)$ and $(Y, \|\cdot\|)$ are Banach spaces.

Define operators $M : X \cap \text{dom}M \rightarrow Y, N_\lambda : X \rightarrow Y$ as follows:

$$M(u, v) = \begin{pmatrix} (\varphi_p(u''))'(t) \\ (\varphi_p(v''))'(t) \\ T_1(\varphi_p(u''))'(t) \\ T_2(\varphi_p(v''))'(t) \end{pmatrix}, N_\lambda(u, v) = \begin{pmatrix} \lambda f(t, v(t)v'(t), v''(t)) \\ \lambda g(t, u(t), u'(t), u''(t)) \\ 0 \\ 0 \end{pmatrix}$$

where $T_i y = c_i, i = 1, 2, y \in C[0, 1], c_1, c_2$ satisfy

$$\int_0^1 k_i(t) \int_t^1 \varphi_q(\int_0^s (y(r) - c_i) dr) ds dt = 0 \quad (0.1)$$

$$\text{dom}M = \{(u, v) \in X | \varphi_p(u''), \varphi_p(v'') \in C^1[0, 1], u(0) = u''(0) = v(0) = v''(0) = 0\}$$

Lemma3.1 For $y \in C[0, 1]$, there is only one constant $c_i \in R$ such that $T_i y = c_i$, with $|c_i| \leq \|y\|_\infty$, and $T_i : C[0, 1] \rightarrow R, i = 1, 2$, are continuous.

The proof is similar to Lemma 3.1 in [Weihua, 2014].

It is clear that $(u, v) \in \text{dom}M$ is a solution if and only if it satisfies $M(u, v) = N(u, v)$ where $N = N_1$. For convenience,

$$\text{let } (a, b, c, d)^L = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

Lemma3.2 M is a quasi-linear operator.

Proof. It is easy to get $\text{Ker}M = \{(b_1 t, b_2 t) | b_1, b_2 \in R\} := X_1$.

For $(u, v) \in X \cap \text{dom}M$, if $M(u, v) = (y_1, y_2, c_1, c_2)^L$, then c_1, c_2 satisfy (3.1). On the other hand, if $y_i \in C[0, 1], T_i y_i = c_i, i = 1, 2$, take

$$\begin{pmatrix} u(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} \int_0^t (t-s) \varphi_q(\int_0^s y_1(r) dr) ds \\ \int_0^t (t-s) \varphi_q(\int_0^s y_2(r) dr) ds \end{pmatrix}.$$

We can get $(u, v) \in X \cap \text{dom}M$ and $M(u, v) = (y_1, y_2, c_1, c_2)^L$, then c_1, c_2 . Thus

$$\text{Im}M = \{(y_1, y_2, c_1, c_2)^L | y \in C[0, 1], c_1, c_2 \text{ satisfy (3.1)}\}.$$

By the continuity of $T_i, i = 1, 2$, we see that $\text{Im}M \subset Y$ is closed. So, M is quasi-linear. The proof is completed.

Lemma3.3 $T_i(c) = c, T_i(y + c) = T_i(y) + c, T_i(cy) = cT_i(y), i = 1, 2, c \in R, y \in C[0, 1]$

Proof. The proof is simple. Therefore we omit it.

Take a projector $P : X \rightarrow X_1$ and an operator $Q : Y \rightarrow Y_1$ as follows:

$$(P(u, v))(t) = (u'(0)t, v'(0)t), Q(y_u, y_v, y_1, y_2)^L = (0, 0, T_1 y_1 - T_1 y_u, T_2 y_2 - T_2 y_v)^L$$

where $Y_1 = \{(0, 0, c_1, c_2)^L \mid c_i \in R, i = 1, 2\}$. Obviously $QY = Y_1$ and $\dim Y_1 = \dim X_1$.

By the continuity and boundedness of $T_i, i = 1, 2$, we can easily see that Q is continuous and bounded in Y . It follows Lemma 3.3 that $Q(I - Q)(y_u, y_v, y_1, y_2)^L = (0, 0, 0, 0)^L, y_u, y_v, y_1, y_2 \in C[0, 1]$

Define a operator $R : X \times [0, 1] \rightarrow X_2$

$$R(u, v, \lambda)(t) = \begin{pmatrix} \int_0^t (t-s) \varphi_q \left(\int_0^s \lambda f(r, v(r), v'(r), v''(r)) dr \right) ds \\ \int_0^t (t-s) \varphi_q \left(\int_0^s \lambda g(r, u(r), u'(r), u''(r)) dr \right) ds \end{pmatrix},$$

where $\text{Ker} M \oplus X_2 = X$. By (H_2) and the Arzela-Asscoli theorem, we can get $R : \bar{\Omega} \times [0, 1] \rightarrow X_2$ is continuous and compact, where $\Omega \subset X$ is a bounded set.

Lemma 3.4 Assume that $\Omega \in X$ is an open bounded set. Then N_λ is M -quasi-compact in $\bar{\Omega}$.

Proof. It is clear that $\text{Im} P = \text{Ker} M, QN_\lambda(u, v) = \theta \Leftrightarrow QN(u, v) = \theta$ and $R(\cdot, \cdot, 0) = 0$. for $(u, v) \in \bar{\Omega}$,

$$\begin{aligned} (I - Q)N_\lambda(u, v) &= \begin{pmatrix} \lambda f(t, v(t), v'(t), v''(t)) \\ \lambda g(t, u(t), u'(t), u''(t)) \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ T_1(\lambda f(t, v(t), v'(t), v''(t))) \\ T_2(\lambda g(t, u(t), u'(t), u''(t))) \end{pmatrix} \\ &= \begin{pmatrix} \lambda f(t, v(t), v'(t), v''(t)) \\ \lambda g(t, u(t), u'(t), u''(t)) \\ T_1(\lambda f(t, v(t), v'(t), v''(t))) \\ T_2(\lambda g(t, u(t), u'(t), u''(t))) \end{pmatrix} \in \text{Im} M. \end{aligned}$$

Since $\text{Im} M \subset \text{Ker} Q$, and $y = Qy + (I - Q)y$, we obtain $\text{Im} M \subset (I - Q)Y$. Thus $(I - Q)N_\lambda(\bar{\Omega}) \subset \text{Im} M \subset (I - Q)Y$. For $(u, v) \in \Sigma_\lambda = \{(u, v) \in \bar{\Omega} \cap \text{dom} M \mid M(u, v) = N_\lambda(u, v)\}$

$$\begin{aligned} R(u, v, \lambda) &= \begin{pmatrix} \int_0^t (t-s) \varphi_q \left(\int_0^s \lambda f(r, v(r), v'(r), v''(r)) dr \right) ds \\ \int_0^t (t-s) \varphi_q \left(\int_0^s \lambda g(r, u(r), u'(r), u''(r)) dr \right) ds \end{pmatrix} \\ &= \begin{pmatrix} \int_0^t (t-s) \varphi_q \left(\int_0^s \varphi_p(u'')'(r) dr \right) ds \\ \int_0^t (t-s) \varphi_q \left(\int_0^s \varphi_p(v'')'(r) dr \right) ds \end{pmatrix} \\ &= \begin{pmatrix} u(t) - u'(0)t \\ v(t) - v'(0)t \end{pmatrix} = (I - P)(u, v). \end{aligned}$$

i.e. Definition 2.2(c) holds. For $u \in \bar{\Omega}$, we have

$$M[P(u, v) + R(u, v, \lambda)] = \begin{bmatrix} \lambda f(r, v(r), v'(r), v''(r)) \\ \lambda g(t, u(t), u'(t), u''(t)) \\ T_1(\lambda f(t, v(t), v'(t), v''(t))) \\ T_2(\lambda g(t, u(t), u'(t), u''(t))) \end{bmatrix} = (I - Q)N_\lambda(u, v)$$

Thus, Definition 2.2(d) holds. Therefore, N_λ is M -quasi-compact in $\bar{\Omega}$. The proof is completed.

Theorem 3.1 Assume that the following conditions hold:

(H_3) There exist nonnegative constants K_1, K_2 such that one of (1) and (2) holds:

(1)

$$B_1 f(t, A_1, B_1, C_1) > 0, \quad t \in [0, 1], |B_1| > K_1, A_1, C_1 \in R$$

and

$$B_2 g(t, A_2, B_2, C_2) > 0, \quad t \in [0, 1], |B_2| > K_2, A_2, C_2 \in R$$

(2)

$$B_1 f(t, A_1, B_1, C_1) < 0, \quad t \in [0, 1], |B_1| > K_1, A_1, C_1 \in R$$

and

$$B_2 g(t, A_2, B_2, C_2) < 0, \quad t \in [0, 1], |B_2| > K_2, A_2, C_2 \in R$$

(H₄) There exist nonnegative functions $a_i(t), b_i(t), c_i(t), e_i(t) \in L^1[0, 1], i = 1, 2$ such that

$$|f(t, x, y, z)| \leq a_1(t)\varphi_p(|x|) + b_1(t)\varphi_p(|y|) + c_1(t)\varphi_p(|z|) + e_1(t)$$

and

$$|g(t, x, y, z)| \leq a_2(t)\varphi_p(|x|) + b_2(t)\varphi_p(|y|) + c_2(t)\varphi_p(|z|) + e_2(t)$$

where $\varphi_q(\|a_i(t)\|_1 + \|b_i(t)\|_1 + \|c_i(t)\|_1) < 2^{2-q}$ if $1 < p \leq 2$; $\varphi_q(2^{p-2}\|a_i(t)\|_1 + 2^{p-2}\|b_i(t)\|_1 + \|c_i(t)\|_1) < 1$ if $p \geq 2$
The boundary value problem (1.1) has at least one solution.

Lemma3.5 Suppose (H₃) and (H₄) hold. Then

$$\Omega_1 = \{(u, v) \in \text{dom}M \mid M(u, v) = N_\lambda(u, v)\}$$

is bounded in X .*Proof.* For $(u, v) \in \Omega_1$, we have $QN_\lambda(u, v) = 0$, i.e.

$$T_1(\lambda f(t, v(t), v'(t), v''(t))) = 0, T_2(\lambda g(t, u(t), u'(t), u''(t))) = 0$$

By H₃, there exist constants $t_0, t_1 \in [0, 1]$ such that $|u'(t_0)| \leq K_2$ and $|v'(t_1)| \leq K_1$. Since $u(t) = \int_0^t u'(s)ds$,

$$u'(t) = u'(t_0) + \int_{t_0}^t u''(s)ds, v(t) = \int_0^t v'(s)ds, v'(t) = v'(t_1) + \int_{t_1}^t v''(s)ds, \text{ then that}$$

$$\begin{aligned} |u(t)| &\leq \|u'\|_\infty, |u'(t)| \leq K_2 + \|u''\|_\infty, \quad t \in [0, 1]. \\ |v(t)| &\leq \|v'\|_\infty, |v'(t)| \leq K_1 + \|v''\|_\infty, \quad t \in [0, 1]. \end{aligned} \quad (0.2)$$

It follow from $M(u, v) = N_\lambda(u, v)$, (H₄) and (3.2) that

$$\begin{aligned} |u''(t)| &= |\varphi_q(\int_0^t \lambda f(s, v(s), v'(s), v''(s))ds)| \\ &\leq \varphi_q(\int_0^1 a_1(t)\varphi_p(|v|) + b_1(t)\varphi_p(|v'|) + c_1(t)\varphi_p(|v''|) + e_1(t)dt) \\ &\leq \varphi_q[(\|a_1\|_1 + \|b_1\|_1)\varphi_p(K_1 + \|v''\|_\infty) + \|c_1\|_1\varphi_p(\|v''\|_\infty) + \|e_1\|_1] \end{aligned}$$

If $1 < p \leq 2$, by Lemma 2.1, we get

$$\begin{aligned} |u''(t)| &\leq \varphi_q(D_1 + C_1\varphi_p\|v''\|_\infty) \\ &\leq 2^{q-2}[\varphi_q(D_1) + \varphi_q(C_1)\|v''\|_\infty] \\ &\leq 2^{q-2}[\varphi_q(D_1) + \varphi_q(C_1)\|v\|] \end{aligned}$$

thus

$$\|u''\|_\infty \leq 2^{q-2}[\varphi_q(D_1) + \varphi_q(C_1)\|v\|]$$

where $C_1 = \|a_1\|_1 + \|b_1\|_1 + \|c_1\|_1$, $D_1 = (\|a_1\|_1 + \|b_1\|_1)\varphi_p(K_1) + \|e_1\|_1$. On the other hand, since $|u'(t)| \leq K_2 + \|u''\|_\infty, t \in [0, 1]$, we get $\|u'\|_\infty \leq K_2 + \|u''\|_\infty$ since $|u(t)| \leq \|u'\|_\infty, t \in [0, 1]$, we get $\|u\|_\infty \leq K_2 + \|u''\|_\infty$. Thus

$$\|u\| \leq K_2 + 2^{q-2}[\varphi_q(D_1) + \varphi_q(C_1)\|v\|]. \quad (0.3)$$

Similarly,

$$\|v\| \leq K_1 + 2^{q-2}[\varphi_q(D_2) + \varphi_q(C_2)\|u\|] \quad (0.4)$$

where $C_2 = \|a_2\|_1 + \|b_2\|_1 + \|c_2\|_1$, $D_2 = (\|a_2\|_1 + \|b_2\|_1)\varphi_p(K_2) + \|e_2\|_1$. Take $M_1 = \max\{2^{q-2}\varphi_q(C_1), 2^{q-2}\varphi_q(C_2)\}$, we get

$$\|u\| \leq K_2 + 2^{q-2}\varphi_q(D_1) + M_1\|v\|,$$

$$\|v\| \leq K_1 + 2^{q-2}\varphi_q(D_2) + M_1\|u\|.$$

Since $\|(u, v)\| = \|u\| + \|v\|$, we get

$$\|(u, v)\| \leq \frac{K_1 + K_2 + 2^{q-2}\varphi_q(D_1) + 2^{q-2}\varphi_q(D_2)}{1 - M_1}$$

If $p > 2$, by Lemma 2.1, we get

$$\begin{aligned} |u''(t)| &\leq \varphi_q(D_3 + C_3\varphi_p\|v''\|_\infty) \leq \varphi_q(D_3) + \varphi_q(C_3)\|v''\|_\infty \\ &\leq \varphi_q(D_3) + \varphi_q(C_3)\|v\|, \end{aligned}$$

thus

$$\|u''\|_\infty \leq \varphi_q(D_3) + \varphi_q(C_3)\|v\|.$$

By (3.2), we get

$$\|u\| \leq K_2 + \varphi_q(D_3) + \varphi_q(C_3)\|v\|.$$

Similarly

$$\|v\| \leq K_1 + \varphi_q(D_4) + \varphi_q(C_4)\|v\|.$$

where $C_3 = 2^{p-2}(\|a_1\|_1 + \|b_1\|_1) + \|c_1\|_1$, $D_3 = 2^{p-2}(\|a_1\|_1 + \|b_1\|_1)\varphi_p(K_1) + \|e_1\|_1$, $C_4 = 2^{p-2}(\|a_2\|_1 + \|b_2\|_1) + \|c_2\|_1$, $D_4 = 2^{p-2}(\|a_2\|_1 + \|b_2\|_1)\varphi_p(K_2) + \|e_2\|_1$. Take $M_2 = \max\{\varphi_q(C_3), \varphi_q(C_4)\}$, we get

$$\|(u, v)\| \leq \frac{K_1 + K_2 + \varphi_q(D_3) + \varphi_q(D_4)}{1 - M_2}$$

So we obtain Lemma 3.5.

Remark 1 If we take $\|(u, v)\| = \max\{\|u\|, \|v\|\}$, Lemma 3.5 still holds. We only need (3.3) into (3.4), we can obtain the Lemma.

Lemma 3.6 Assume (H_3) holds, then

$$\Omega_2 = \{(u, v) \in \text{Ker}M \mid QN(u, v) = 0\}$$

is bounded in X , where $N = N_1$.

Proof. For $(u, v) \in \Omega_2$, we have $(u, v) = (b_1t, b_2t)$, then $T_1f(t, b_2t, b_2, 0) = 0$, $T_2f(t, b_1t, b_1, 0) = 0$. By (H_3) , we get $|b_1| \leq K_2$, $|b_2| \leq K_1$. So, Ω_2 is bounded.

Proof of theorem 3.1 Let $\Omega = \{(u, v) \in X \mid \|(u, v)\| < r\}$, where r is large enough such that $K_1 + K_2 < r < +\infty$ and $\Omega_1 \cup \Omega_2 \subset \Omega$.

By lemma 3.5 and Lemma 3.6, we can get if $(u, v) \in \text{dom}M \cap \partial\Omega$, then $M(u, v) \neq N_\lambda(u, v)$, if $(u, v) \in \text{Ker}M \cap \partial\Omega$, then $QN(u, v) \neq 0$.

Let

$$H(u, v, \delta) = \rho\delta(u, v)^L + (1 - \delta)JQN(u, v)^L, \delta \in [0, 1], (u, v) \in \text{Ker}M \cap \overline{\Omega}.$$

where $J : \text{Im}Q \rightarrow \text{Ker}M$ is a homeomorphism with $J(0, 0, b_1, b_2)^L = (b_2t, b_1t)^L$,

$$\rho = \begin{cases} -1 & , \text{ if } (H_3)(1) \text{ holds} \\ 1 & , \text{ if } (H_3)(2) \text{ holds} \end{cases}$$

$$\text{sgn}(x) = \begin{cases} 1 & , x > 0 \\ -1 & , x < 0 \end{cases}$$

For $(u, v) \in \text{Ker}M \cap \partial\Omega$, we have $(u, v) = (b_1t, b_2t) \neq (0, 0)$

$$H(u, v, \delta) = \rho\delta \begin{pmatrix} b_1t \\ b_2t \end{pmatrix} + (1 - \delta) \begin{pmatrix} -T_2g(t, b_1t, b_1, 0)t \\ -T_1f(t, b_2t, b_2, 0)t \end{pmatrix}$$

If $\delta = 1$, $h(u, v, 1) = \rho(b_1t, b_2t)^L \neq (0, 0)^L$. If $\delta = 0$, $h(u, v, 0) = JQN(b_1t, b_2t)^L \neq (0, 0)^L$. For $0 < \delta < 1$, we now prove that $H(u, v, \delta) \neq (0, 0)^L$. Otherwise, If $H(u, v, \delta) = (0, 0)^L$, then

$$\begin{pmatrix} T_2g(t, b_1t, b_1, 0) \\ T_1f(t, b_2t, b_2, 0) \end{pmatrix} = \begin{pmatrix} \frac{\rho\delta}{1-\delta}b_1 \\ \frac{\rho\delta}{1-\delta}b_2 \end{pmatrix}$$

Since $\|(u, v)\| = r > K_1 + K_2$, we have $|b_1| > K_2$ or $|b_2| > K_1$. If $|b_2| > K_1$ we have

$$T_1(b_2 f(t, b_2 t, b_2, 0)) = b_2 T_1(f(t, b_2 t, b_2, 0)) = \frac{\rho \delta}{1 - \delta} b_2^2$$

$$\operatorname{sgn}(T_1(b_2 f(t, b_2 t, b_2, 0))) = \operatorname{sgn}[b_2 f(t, b_2 t, b_2, 0)] = \operatorname{sgn}\left(\frac{\rho \delta}{1 - \delta} b_2^2\right) = \operatorname{sgn}(\rho)$$

if $|b_1| > K_2$, we have

$$T_2(b_1 g(t, b_1 t, b_1, 0)) = b_1 T_2(g(t, b_1 t, b_1, 0)) = \frac{\rho \delta}{1 - \delta} b_1^2$$

$$\operatorname{sgn}(T_2(b_1 g(t, b_1 t, b_1, 0))) = \operatorname{sgn}[b_1 g(t, b_1 t, b_1, 0)] = \operatorname{sgn}\left(\frac{\rho \delta}{1 - \delta} b_1^2\right) = \operatorname{sgn}(\rho)$$

This is a contradiction with the definition of ρ . So, $H(u, v, \delta) \neq 0$, $(u, v) \in \operatorname{Ker} M \cap \partial \Omega$, $\delta \in [0, 1]$.

By the homotopy of degree, we get $\deg(JQN, \Omega \cap \operatorname{Ker} M, 0) = \deg(H(\cdot, \cdot, 0), \Omega \cap \operatorname{Ker} M, 0) = \deg(H(\cdot, \cdot, 1), \Omega \cap \operatorname{Ker} M, 0) = \deg(\rho I, \Omega \cap \operatorname{Ker} M, 0) \neq 0$. By Theorem 2.1, we find that (1.1) has at least one solution in $\bar{\Omega}$. The proof is completed.

Remark 2 If $\|(u, v)\| = \max\{\|u\|, \|v\|\}$, Lemma 3.6 still holds. We can take $\max\{K_1, K_2\} < r < \infty$, we still get the Theorem 3.1.

4. Example

Let us consider the following boundary value problem

$$\begin{cases} (\varphi_p(u''))'(t) = \frac{t^3}{4} \sin x^5 + \frac{1}{8} y^5 + \frac{t^2}{4} \sin z^5 + \cos t \\ (\varphi_p(v''))'(t) = \frac{t^3}{8} \cos x^5 + \frac{1}{16} y^5 + \frac{t^3}{12} \cos z^5 + \sin t \\ u(0) = u''(0) = 0, v(0) = v''(0) = 0 \\ u'(1) = \int_0^1 2tu'(t)dt, v'(1) = \int_0^1 3t^2v'(t)dt \end{cases} \quad (4.1)$$

where $p = 6$.

Corresponding to problem (1.1), we have $q = \frac{6}{5}$, $a_1(t) = \frac{t^3}{4}$, $b_1(t) = \frac{1}{8}$, $c_1(t) = \frac{t^2}{4}$, $e_1(t) = \cos t$, $k_1(t) = 2t$, $a_2(t) = \frac{t^4}{8}$, $b_2(t) = \frac{1}{16}$, $c_2(t) = \frac{t^3}{12}$, $e_1(t) = \sin t$, $k_2(t) = 3t^2$. Take $K_1 = 2$, $K_2 = 3$, we can get $(H_1) - (H_4)$ hold. By Theorem 3.1, we have the problem (4.1) has at least one solution.

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