

A Class of Linear Boundary Value Problem for k -regular Functions in Clifford Analysis

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Received: April 16, 2016 Accepted: April 24, 2016 Online Published: May 18, 2016

doi:10.5539/jmr.v8n3p57

URL: <http://dx.doi.org/10.5539/jmr.v8n3p57>

Abstract

In this paper, we introduce the linear boundary value problem for k -regular function, and give an unique solution for this problem by integral equation method and fixed-point theorem.

Keywords: k -regular function, Clifford analysis

1. Introduction

The boundary value problem is one of the important aspects in Clifford analysis. This problem on bounded domains has seen great achievements. [Wen, 1991; Huang, 1996; Zhang et al., 2001] have discussed Riemann-Hilbert boundary value problems of regular function on bounded domains. [Li, 2007] characterized boundary value problems of k -regular functions. In this paper, we introduce the *linear* boundary value problem of k -regular function, and give an unique solution to this problem by integral equation method and fixed-point theorem.

Let n be a positive integer, and $\{e_0, e_1, \dots, e_n\}$ be basis for the Euclidean space \mathbb{R}^{n+1} . We denote by \mathcal{A} the 2^n dimensional real Clifford algebra, which is generated by \mathbb{R}^{n+1} ; denote the basis of \mathcal{A} by $e_A = e_{\alpha_1, \alpha_2, \dots, \alpha_h}$, $A = \{\alpha_1, \alpha_2, \dots, \alpha_h\} \subseteq \{1, 2, \dots, n\}$, $1 \leq \alpha_1 < \alpha_2 < \dots < \alpha_h \leq n$. In particular, if $A = \emptyset$, $e_\emptyset = e_0$. So, for an arbitrary $u \in \mathcal{A}$, we have $u = \sum_A u_A e_A$ with $u_A \in \mathbb{R}$. In \mathcal{A} , we have

$$e_i^2 = -1, e_i e_j = -e_j e_i \text{ for } i \neq j, i, j = 1, 2, \dots, n,$$

that is so-called combinative and incommutable multiplication rule of Clifford algebra. For $u \in \mathcal{A}$, we write $u^* = \sum_A (-1)^{\frac{|A|(|A|-1)}{2}} u_A e_A$, $u' = \sum_A (-1)^{\frac{|A|}{2}} u_A e_A$ and $|u|$ for its module, where $|A|$ is the cardinality of the index set A . Define $|u|^2 = \sum_A |u_A|^2$; \bar{u} its conjugate with $\bar{u} = (u^*)'$, where $u^* = \sum_A (-1)^{\frac{|A|(|A|-1)}{2}} u_A e_A$, and $u' = \sum_A (-1)^{|A|} u_A e_A$. For $u, v \in \mathcal{A}$, we have

$$|u + v| \leq |u| + |v|, |uv| \leq 2^n |u| |v|.$$

Let D be a region in \mathbb{R}^{n+1} . For a differentiable function $f : D \rightarrow \mathcal{A}$ with $f(x) = \sum_A f_A(x) e_A$, we say f is a *regular function* if

$$\bar{\partial} f = \sum_{i=0}^n e_i \frac{\partial f}{\partial x_i} = \sum_{i=0}^n \sum_A e_i e_A \frac{\partial f_A}{\partial x_i} = 0,$$

and a k -regular function if $\bar{\partial}^k f = 0$, where the operator $\bar{\partial} = \sum_{j=0}^n \frac{\partial}{\partial x_j} e_j$. Let $\Omega \subset \mathbb{R}^{n+1}$ be an unbounded domain with smooth oriented Liapunov boundary $\partial\Omega$, and Ω^c , the complementary set of Ω containing a non-empty open set. We denote the bounded Hölder continuous function on $\partial\Omega$ in order of β ($0 < \beta < 1$) by $H(\partial\Omega, \beta)$. For $f \in H(\partial\Omega, \beta)$, we define its norm by

$$\|f\|_\beta = \sup_{t \in \partial\Omega} |f(t)| + \sup_{t_1 \neq t_2} \frac{|f(t_1) - f(t_2)|}{|t_1 - t_2|}.$$

Then $H(\partial\Omega, \|\cdot\|_\beta)$ is a Banach space. And for $f, g \in H(\partial\Omega, \|\cdot\|_\beta)$, we have

$$\|f + g\|_\beta \leq \|f\|_\beta + \|g\|_\beta, \|fg\|_\beta \leq 2^n \|f\|_\beta \|g\|_\beta.$$

2. Main Result

In what follows, we denote by Ω a non-empty connected open set in \mathbb{R}^{n+1} with smooth oriented Liapunov boundary $\partial\Omega$, and by w_n the area of unit ball in \mathbb{R}^{n+1} . We first give the linear boundary value problem for k -regular function.

Definition 2.1. Let $A(t), B(t), g_l(t) \in H(\partial\Omega, \beta)$, $1 \leq l \leq k$. Write $\Omega^+ = \Omega$, $\Omega^- = \mathbb{R}^{n+1} \setminus \bar{\Omega}$ with $\bar{\Omega} = \Omega \cup \partial\Omega$. If there exists some function ϕ such that

- 1) ϕ is a k -regular function on Ω^\pm ;
 2)

$$\begin{cases} \phi^+(t)A(t) + \phi^-(t)B(t) = g_1(t) \\ \bar{\partial}\phi^+(t)A(t) + \bar{\partial}\phi^-(t)B(t) = g_2(t) \\ \vdots \\ \bar{\partial}^{k-1}\phi^+(t)A(t) + \bar{\partial}^{k-1}\phi^-(t)B(t) = g_k(t) \end{cases} \quad (1)$$

Then we say ϕ is a solution to the linear boundary problem. And this problem is also called linear boundary problem for k -regular function.

The following lemmas are borrowed from [Li, 2007]:

Lemma 2.1. Let $f(x)$ be a k -regular function on Ω . Then we have

$$f(x) = \sum_{m=0}^{k-1} \frac{1}{m!} x_0^m f_m(x), \quad (2)$$

where $f_m, m = 0, 1, \dots, k-1$ are regular functions defined on Ω .

Lemma 2.2 Here we give Plemelj equation for regular function:

$$\phi_m^\pm = \pm \frac{1}{2} \varphi_m + \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau-x}}{|\tau-x|^{n+1}} m(\tau) \varphi_m(\tau) d_{s_\tau}. \quad (3)$$

where $m(u)$ is the unit vector in $\partial\Omega$'s normal direction, and $\varphi_j \in H(\partial\Omega, \beta)$, $j = 0, 1, \dots, k-1$. Then ϕ is a regular function on $\mathbb{R}^{n+1} \setminus \partial\Omega$.

The following lemma is borrowed from [Xu et al., 2008]

Lemma 2.3. Let $\phi \in H(\partial\Omega, \beta)$. Define a operator K on $H(\partial\Omega, \beta)$ by

$$(K\phi)(x) = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau-x}}{|\tau-x|^n} m(\tau) \phi(\tau) d_{s_\tau} \quad (4)$$

for $x \in \partial\Omega$. Then there exists some $C > 0$ such that $\|K \cdot\| \leq C\|\cdot\|$ on $H(\partial\Omega, \beta)$.

Theorem 2.1. Let $A(t), B(t), g_l(t), (1 \leq l \leq k) \in H(\partial\Omega, \beta)$. If

$$\begin{aligned} \zeta &= 2^n \left[\left(\frac{1}{2} + C \right) (\|A + B\|) + \|1 - B\| \right] \in (0, 1), \\ \|g'_{m+1}\|_\beta &\leq M(1 - \zeta), \end{aligned} \quad (5)$$

where C is in Lemma 2.3, then the solution of the m -th equation in (1) is given by

$$\phi(x) = \sum_{m=0}^{k-1} \frac{1}{m!} x_1^m \phi_m(x)$$

with

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau-x}}{|\tau-x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau}$$

for $m = 0, 2, \dots, k-1$.

Proof. Substituting (2) into (1), we have

$$T \begin{pmatrix} \phi_0^+ \\ \vdots \\ \phi_{k-2}^+ \\ \phi_{k-1}^+ \end{pmatrix} A + T \begin{pmatrix} \phi_0^- \\ \vdots \\ \phi_{k-2}^- \\ \phi_{k-1}^- \end{pmatrix} B = \begin{pmatrix} g_1 \\ \vdots \\ g_{k-1} \\ g_k \end{pmatrix} \quad (6)$$

where

$$T = \begin{pmatrix} 0 & 0 & 0 & \cdots & 1 \\ 0 & 1 & x_1 & \cdots & \frac{1}{(k-2)!} x_1^{k-2} \\ \vdots & \vdots & \vdots & & \\ 1 & x_1 & \frac{1}{2!} x_1^2 & \cdots & \frac{1}{(k-1)!} x_1^{k-1} \end{pmatrix}.$$

We rewrite (6) as

$$\begin{pmatrix} \phi_0^+ & A \\ \vdots & \vdots \\ \phi_{k-2}^+ & A \\ \phi_{k-1}^+ & A \end{pmatrix} + \begin{pmatrix} \phi_0^+ & B \\ \vdots & \vdots \\ \phi_{k-2}^+ & B \\ \phi_{k-1}^+ & B \end{pmatrix} = \begin{pmatrix} g'_1 \\ \vdots \\ g'_{k-1} \\ g'_k \end{pmatrix} \quad \text{with} \quad \begin{pmatrix} g'_1 \\ \vdots \\ g'_{k-1} \\ g'_k \end{pmatrix} = T^{-1} \begin{pmatrix} g_1 \\ \vdots \\ g_{k-1} \\ g_k \end{pmatrix},$$

which is equivalent to

$$\begin{cases} \phi_0^+ A + \phi_0^- B = g'_1 \\ \phi_1^+ A + \phi_1^- B = g'_2 \\ \vdots \\ \phi_{k-1}^+ A + \phi_{k-1}^- B = g'_k, \end{cases} \quad (7)$$

herein ϕ_m is a regular function given by

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau} \quad (8)$$

for $m = 0, \dots, k-1$. Next, to finish the proof, we only need to prove that ϕ_m ($0 \leq m \leq k-1$) given by (8) are solutions to (7). By substituting (3) into (7), we have

$$\left(\frac{1}{2}\varphi_m + K\varphi_m\right)A + \left(-\frac{1}{2}\right)\varphi_m + K\varphi_m B = g'_{m+1} \quad m = 0, \dots, k-1. \quad (9)$$

Write

$$L\phi_m = \left(\frac{1}{2}\varphi_m + K\varphi_m\right)(A+B) + \varphi_m(1-B) - g'_{m+1},$$

then (9) can be rewritten as $L\phi_m = \phi_m$. Let $T = \{\varphi | \varphi \in H(\partial\Omega, \beta), \|\varphi\|_\beta \leq M\}$. Then T is a closed subspace of $H(\partial\Omega, \beta)$. Since

$$\begin{aligned} \|L\varphi_m\|_\beta &= \left\| \left(\frac{1}{2}\varphi_m + K\varphi_m\right)(A+B) + (1-B)\varphi_m - g'_{m+1} \right\| \\ &\leq 2^n \left[\left(\frac{1}{2} + C\right)(\|A+B\|) + \|1-B\| \right] \|\varphi_m\| + \|g'_{m+1}\| \\ &\leq \zeta \|\varphi_m\| + \|g'_{m+1}\| \\ &\leq M, \end{aligned} \quad (10)$$

F is a map on T . For $\phi'_m, \phi''_m \in T$, we have

$$\|L\phi'_m - L\phi''_m\| \leq \zeta \|\phi'_m - \phi''_m\|_\beta,$$

with $0 < \zeta < 1$, and thus L is a compression map on T . So, there is a unique fixed φ_m such that $L\varphi_m = \varphi_m$ by fixed point theorem, which implies that

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau}$$

is unique solution for the m -th equation in (7). This gives the proof.

Acknowledgements

This work was supported by National Natural Science Foundation of China (Grant No. 11501010). The author thanks the referees for their valuable suggestions, which greatly improve the readability of the article.

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