

Exact Multi-soliton Solution for the (3+1)-D Jimbo-Miwa Equation

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Abstract

In this paper, by using bilinear form and extended three-wave type of ansatz approach, we obtain new multi-soliton solutions of the (3+1)-dimensional Jimbo-Miwa equation, including the periodic breather-type of kink three-soliton solutions, the cross-kink four-soliton solutions, the doubly periodic breather-type of soliton solutions and the doubly periodic breather-type of cross-kink two-soliton solutions. It is shown that the generalized three-wave method, with the help of symbolic computation, provides an effective and powerful mathematical tool for solving high dimensional nonlinear evolution equations in mathematical physics.

Keywords: Jimbo-Miwa equation, Extended three-wave method, Multi-soliton solution

1. Introduction

It is well known that many important phenomena in physics and other fields are described by nonlinear partial differential equations. As mathematical models of these phenomena, the investigation of exact solutions is important in mathematical physics. Many methods are available to look for exact solutions of nonlinear evolution equations, such as the inverse scattering method, the Lie group method, the mapping method, Exp-function method, ansatz technique, three-wave type of ansatz approach and so on (Ma and Fan(2011), Liu et al.(2005), Dai et al.(2005)). In this paper, we consider the following Jimbo-Miwa equation:

$$u_{xxxy} + 3u_x u_{xy} + 3u_{xx} u_y + 2u_{yt} - 3u_{xz} = 0 \quad (1)$$

By means of the two-soliton method and bilinear methods, the two-soliton solutions, three-wave solutions of the Jimbo-Miwa were found as well as (Dai et al.(2007), Li et al.(2011)).

In this paper, we discuss further the (3 + 1)-dimensional Jimbo-Miwa equation, by using bilinear form and extend three-wave type of ansatz approach, respectively (Xu and Xian (2010), Chow(2002), Xu and Liu (2010)), Some new multi-soliton solutions are obtained.

2. The multi-soliton solutions

We assume

$$u = 2(\ln f)_x \quad (2)$$

where $f = f(x, y, z, t)$ is unknown real function. Substituting Eq.(2) into Eq.(1), we can reduce Eq.(1) into the following Hirota bilinear equation

$$(D_x^3 D_y + 2D_y D_t - 3D_x D_z) f \cdot f = 0 \quad (3)$$

where the Hirota bilinear operator D is defined by ($n, m \geq 0$)

$$D_x^m D_t^n f(x, t) \cdot g(x, t) = \left(\frac{\partial}{\partial x} - \frac{\partial}{\partial x'} \right)^m \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial t'} \right)^n [f(x, t) g(x', t')] \Big|_{x'=x, t'=t} \quad (4)$$

Now we suppose the solution of Eq.(3) as

$$f = e^{-\xi} + \delta_1 \cos(\eta) + \delta_2 \sinh(\gamma) + \delta_3 \cosh(\theta) + \delta_4 e^{\xi} \quad (5)$$

where $\xi = a_1x + b_1y + c_1z + d_1t$, $\eta = a_2x + b_2y + c_2z + d_2t$, $\gamma = a_3x + b_3y + c_3z + d_3t$, $\theta = a_4x + b_4y + c_4z + d_4t$, and $a_i, b_i, c_i, d_i (i = 1, 2, 3, 4)$ are some constants to be determined later. Substituting Eq.(5) into Eq.(3) and equating all the coefficients of different powers of $e^{\xi}, e^{-\xi}, \sin(\eta), \cos(\eta), \sinh(\gamma), \cosh(\gamma), \sinh(\theta), \cosh(\theta)$ and constant term to zero, we can obtain a set of algebraic equations for $a_i, b_i, c_i, d_i, \delta_j (i = 1, 2, 3, 4; j = 1, 2, 3, 4)$. Solving the system with the aid of Maple, we get the following results:

Case(I):

$$\begin{cases} a_1 = 0, a_3 = 0, b_2 = 0, b_4 = 0, c_2 = 0, c_3 = \frac{b_3c_1}{b_1}, c_4 = 0, d_1 = 0, d_3 = 0 \\ d_2 = \frac{a_2(a_2^2b_1 - 3c_1)}{2b_1}, d_4 = -\frac{a_4(3c_1 + a_4^2b_1)}{2b_1}, \delta_1 = \delta_1, \delta_2 = \delta_2, \delta_3 = \delta_3, \delta_4 = \delta_4 \end{cases} \quad (6)$$

where $a_2, a_4, b_1, b_3, c_1, \delta_1, \delta_2, \delta_3, \delta_4$ are some free real constants. Substituting Eq.(6) into Eq.(5) and taking $\delta_4 > 0$, we have

$$f_1 = 2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cosh(a_4 - H_1t) \quad (7)$$

where $K_1 = \frac{a_2(a_2^2b_1 - 3c_1)}{2b_1}$, $L_1 = \frac{b_3c_1}{b_1}$, $H_1 = \frac{a_4(3c_1 + a_4^2b_1)}{2b_1}$. Substituting Eq.(7) into Eq. (2) yields the periodic breather-type of kink three-soliton solutions for Jimbo-Miwa equation as follows:

$$u_1 = -\frac{2[a_2\delta_1 \sin(a_2x + K_1t) - a_4\delta_3 \sinh(a_4x - H_1t)]}{2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cosh(a_4 - H_1t)). \quad (8)$$

The figure of u_1 as $\delta_1 = \frac{1}{2}, \delta_2 = \frac{1}{4}, t = 0$ refer Fig. (a).

If taking $a_2 = iA_2$ in Eq.(7), then we have

$$f_2 = 2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cosh(A_2x - K_2t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cosh(a_4 - H_1t) \quad (9)$$

where $\delta_4 > 0, K_2 = \frac{A_2(A_2^2b_1 + 3c_1)}{2b_1}$. Substituting Eq.(9) into Eq.(2) yields the cross-kink four-soliton solutions of Jimbo-Miwa equation as follows:

$$u_2 = \frac{2[A_2\delta_1 \sinh(A_2x - K_2t) + a_4\delta_3 \sinh(a_4x - H_1t)]}{2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cosh(A_2x - K_2t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cosh(a_4 - H_1t)). \quad (10)$$

The figure of u_2 as $\delta_1 = \frac{1}{2}, \delta_2 = \frac{1}{3}, t = 1$ refer Fig. 2.

If taking $a_4 = iA_4$ in Eq.(7), then we have

$$f_3 = 2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cos(A_4 + H_2t) \quad (11)$$

where $\delta_4 > 0, H_2 = \frac{A_4(A_4^2b_1 - 3c_1)}{2b_1}$. Substituting Eq.(11) into Eq.(2) yields the doubly periodic breather-type of soliton solutions for Jimbo-Miwa equation as follows:

$$u_3 = -\frac{2[a_2\delta_1 \sin(a_2x + K_1t) + A_4\delta_3 \sin(A_4x + H_2t)]}{2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) + \delta_2 \sinh(b_3y + L_1z) + \delta_3 \cos(A_4 + H_2t)). \quad (12)$$

The figure of u_3 as $\delta_1 = \frac{1}{3}, \delta_2 = \frac{1}{2}, t = 0$ refer Fig. 3.

If taking $a_4 = iA_4, b_3 = iB_3, \delta_2 = iQ_2$ in Eq.(7), then we have

$$f_4 = 2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) - Q_2 \sin(B_3y + L_2z) + \delta_3 \cos(A_4 + H_2t) \quad (13)$$

where A_4, B_3, Q_2 are some free real constants, $L_2 = \frac{B_3c_1}{b_2}$ and $\delta_3 > 0$. Substituting Eq.(13) into Eq.(2) yields the doubly periodic breather-type of soliton solutions for Jimbo-Miwa equation as follows:

$$u_4 = -\frac{2[a_2\delta_1 \sin(a_2x + K_1t) + A_4\delta_3 \sin(A_4x + H_2t)]}{2\sqrt{\delta_4} \cosh(b_1y + c_1z + \frac{1}{2} \ln(\delta_4) + \delta_1 \cos(a_2x + K_1t) - Q_2 \sin(B_3y + L_2z) + \delta_3 \cos(A_4 + H_2t)). \quad (14)$$

The figure of u_4 as $\delta_1 = 1, \delta_2 = \frac{1}{3}, t = 0$ refer Fig. 4.

Case(II):

$$\begin{cases} a_1 = 0, a_2 = \frac{\sqrt{4-a_4^4}}{a_4}, a_3 = \frac{2i}{a_4}, b_1 = 1, b_2 = 0, b_3 = \frac{ia_4^2}{\sqrt{4-a_4^4}}, b_4 = -\frac{2}{\sqrt{4-a_4^4}}, c_2 = 1 \\ c_3 = \frac{i(a_4^2c_1+2)}{\sqrt{4-a_4^4}}, c_4 = \frac{a_4^2-2c_1}{\sqrt{4-a_4^4}}, d_1 = \frac{3\sqrt{4-a_4^4}}{2a_4}, d_2 = -\frac{(3a_4^2c_1+a_4^4-4)\sqrt{4-a_4^4}}{2a_4^3} \\ d_3 = -\frac{i(3a_4^4+6a_4^2c_1-8)}{2a_4^3}, d_4 = -\frac{3a_4^2c_1+a_4^4-6}{2a_4}, \delta_4 = \frac{a_4^4(\delta_2^2+\delta_3^2-\delta_1^2)+4(\delta_1^2+\delta_2^2+\delta_3^2)}{4(4-a_4^4)} \end{cases} \quad (15)$$

where $a_4, c_1, \delta_1, \delta_2, \delta_3$ are some free real constants. Substituting Eq.(15) into Eq.(5) and taking $M > 0$, we have

$$f_5 = 2\sqrt{M} \cosh(\xi + \frac{1}{2} \ln(M)) + \delta_1 \cos(\eta) + \delta_2 \sin(\gamma) + \delta_3 \cosh(\theta) \quad (16)$$

when $M > 0$. where $\xi = a_1x + y + c_1z + \frac{3\sqrt{4-a_4^4}}{2a_4}t, \eta = \frac{\sqrt{4-a_4^4}}{a_4}x + z - \frac{(3a_4^2c_1+a_4^4-4)\sqrt{4-a_4^4}}{2a_4^3}t, \gamma = \frac{2}{a_4}x + \frac{a_4^2}{\sqrt{4-a_4^4}}y + \frac{(a_4^2c_1+2)}{\sqrt{4-a_4^4}}z - \frac{(3a_4^4+6a_4^2c_1-8)}{2a_4^3}t, \theta = a_4x - \frac{2}{\sqrt{4-a_4^4}}y + \frac{a_4^2-2c_1}{\sqrt{4-a_4^4}}z - \frac{3a_4^2c_1+a_4^4-6}{2a_4}t, M = \frac{a_4^4(\delta_2^2+\delta_3^2-\delta_1^2)+4(\delta_1^2+\delta_2^2+\delta_3^2)}{4(4-a_4^4)}$. Substituting Eq.(16) into Eq.(2), we obtain the doubly periodic breather-type of cross-kink two-soliton solutions for Jimbo-Miwa equation as follows:

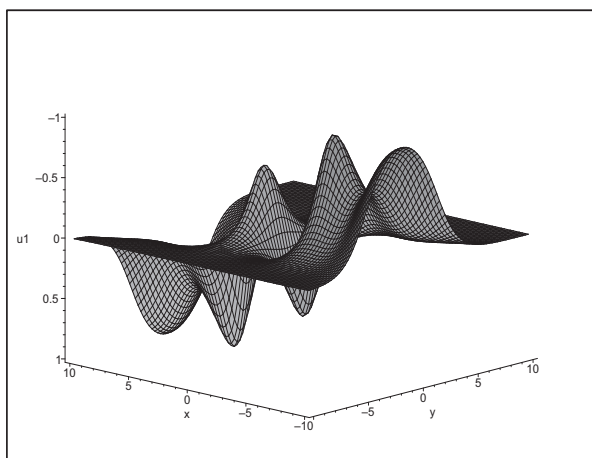
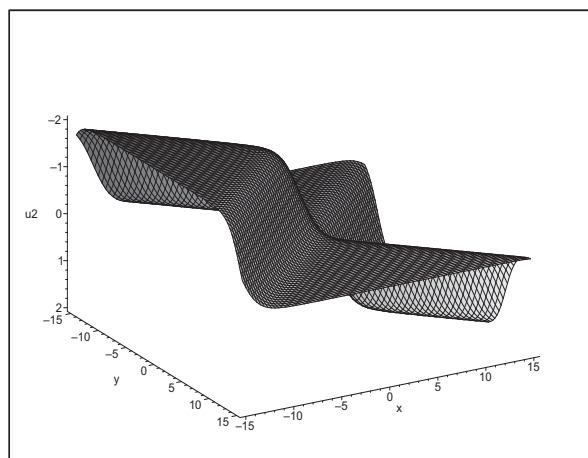
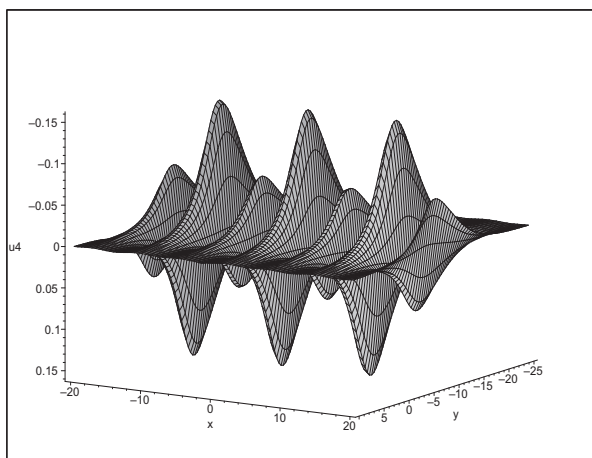
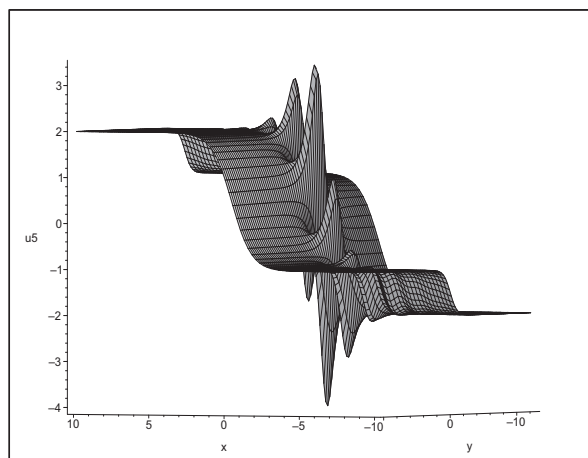
$$u_5 = \frac{2[2a_1\sqrt{M} \sinh(\xi + \frac{1}{2} \ln(M)) + \frac{\delta_1\sqrt{4-a_4^4}}{a_4} \sin(\eta) - \frac{2\delta_2}{a_4} \cos(\gamma) - a_4\delta_3 \sinh(\theta)]}{2\sqrt{M} \cosh(\xi + \frac{1}{2} \ln(M)) + \delta_1 \cos(\eta) + \delta_2 \sin(\gamma) + \delta_3 \cosh(\theta)} \quad (17)$$

3. Conclusion

By using bilinear form and extended three-wave type of ansatz approach, we discuss further the (3 + 1)-dimensional Jimbo-Miwa equation and find some new multi-soliton solutions. The results show that the extended three-wave type of ansatz approach may provide us with a straightforward and effective mathematical tool for seeking multi-wave solutions of higher dimensional nonlinear evolution equations.

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Figure 1. The figure of u_1 as $\delta_1 = \frac{1}{2}, \delta_2 = \frac{1}{4}, t = 0$ Figure 2. The figure of u_2 as $\delta_1 = \frac{1}{2}, \delta_2 = \frac{1}{5}, t = 1$ Figure 3. The figure of u_3 as $\delta_1 = \frac{1}{5}, \delta_2 = \frac{1}{2}, t = 0$ Figure 4. The figure of u_4 as $\delta_1 = 1, \delta_2 = \frac{1}{3}, t = 0$